

November 21, Wednesday

9:00 – 9:15 Opening Ceremony

Room F09

9:15 – 10:00 Plenary talk I

Room F09

Session chair: Tamás Haidegger

63	József Kövecses	Task Level Modelling of Mechanical Systems for Intelligent Robotics
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10:00 – 10:30 Coffee break / Presentation of the Farkas Kempelen chess machine

10:30 – 11:15 Plenary talk II

Room F09

Session chair: Levente Kovács

64	Miklós Kozlovszky	
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11:20 – 12:40 Parallel sessions

11:20 – 12:40 [W1a] Session on Neural Networks

Room F09

Session chair: Sándor Szénási

42	János Hollósi and Claudiu Radu Pozna	Improve the Accuracy of Neural Networks using Capsule Layers
8	Mariia Martynova and Ondrej Kaas	Pre-processing for the RBF-NNs with flexible parameters for multi-dimensional data
29	Ferenc Hegedüs, Tamás Bécsi, Szilárd Aradi and György Gálđi	Hybrid Trajectory Planning for Autonomous Vehicles using Neural Networks
48	Árpád Fehér, Szilárd Aradi and Tamás Bécsi	Q-learning based Reinforcement Learning Approach for Lane Keeping

11:20 – 12:40 [W1b] Session on Neural Networks and Genetic Algorithms

Room F08

Session chair: József K. Tar

34	József Zoltán Szabó and Peter Bakucz	Flexible Neural Tree Based Identification of the Total Dead Center from Large Gas Engine Vibration Signals
1	Bence Dankó and Gábor Kertész	Recognition of the Hungarian Fingerspelling Alphabet using Convolutional Neural Network based on Depth Data
36	József Zoltán Szabó and Peter Bakucz	Convolutional Neural Network Method for Determining the Optimum Number of Transport Data Loggers

12:40 -14:00 Lunch

14:00 – 15:40 Parallel sessions

14:00 – 15:40 [W2a] Session on Applications I

Room F09

Session chair: Dániel Drexler

61	Nina Radojicic and Miroslav Maric	Some possibilities of using fuzzy logic within methods for solving a variant of vehicle routing problem
16	Istvan Kecskes, Ervin Burkus and Peter Odry	Gear efficiency modeling in a simulation model of a DC gearmotor
26	Yahiea Al Naiemy, Taha Elwi and Nagy Lajos	A Folded Microstrip Antenna Structure Based Differential Phase Shift Keying Modulation Technique
50	Balázs Németh, Gergely Sántha and Péter Gáspár	Modeling of driver steering behavior for the control design of automated vehicles
22	Daniel Fenyes, Balazs Nemeth and Peter Gaspar	Control design of variable-geometry suspension systems using a reconfiguration strategy

14:00 – 15:40 [W2b] PhD Student Workshop on Applied Informatics in Computational Intelligence I

Room F08

Session organizer and session chair: László Horváth

2	Judith Jakob and József Tick	CoPeD: Comparable Pedestrian Driver Data Set for Traffic Scenarios
6	Hamza Khan and József Tar	Novel Contradiction Resolution in Fixed Point Transformation-based Adaptive Control
60	Zoltán Fried, Sándor Szénási and Imre Felde	Reconstruction of a heat transfer coefficients by using FWA approach
13	Taliga Miklós, Komoróczki - Steiner Henriette and Kertész Zsolt László	Testing concepts in Safety-Critical Development
15	Hamza Khan, Tamás Faitli, Tamás Szili and József Tar	Preliminary Investigation on the Possible Adaptive Control of an Inverted Pendulum-type Electric Cart
38	Jozsef Kopjak and Gergely Sebestyen	Deep sleep algorithms in battery powered TDMA wireless mesh sensor network

15:40 – 16:00 Coffee break

16:00 – 17:40 Parallel sessions

16:00 – 17:40 [W3a] Session on Informatics I

Room F09

Session chair: György Eigner

59	György Eigner, Máté Siket and Levente Kovács Frantisek Capkovic	Kalman Filtering of Discrete LPV Diabetes Mellitus Model for Control Purposes Modelling and Control of Complex Flexible Manufacturing Systems by Means of Petri Nets
3	Dávid El-Saig, Renáta Nagyné Elek and Tamás Haidegger	A Graphical Tool for Parsing and Inspecting Surgical Robotic Datasets
14	Csaba Biró and Gábor Kusper	BaW 1.0- A problem specific SAT solver for effective strong connectivity testing in large directed graphs
9	Szilárd Nemes and Margit Antal	Performance Evaluation of Gaussian Mixture Models for Inertial Sensor-based Gait Biometrics

16:00 – 17:40 [W3b] Session on Applications II

Room F08

Session chair: György Györök

12	Omar Al-Debagy and Peter Martinek	A Comparative Review of Microservices and Monolithic Architectures
18	György Györök	Continuous Operation Monitoring of Electronic Circuits with Embedded Microcontroller
21	Andras Molnar, Daniel Stojcsics, Zsolt Domozi and Istvan Lovas	Gamma radiation distribution map creation using a small-sized drone
31	László Juhász	The Fourth Industrial Revolution in Hungary
54	Emőke Imre, Csaba Hegedűs and Sándor Kovács	Some comments on the non-linear model fitting

17:00 MFT meeting

Room F07

18:00 Welcome Reception

November 22, Thursday

9:00 – 10:40 Parallel sessions

9:00 – 10:40 [T1a] Session on Informatics and Modeling Uncertainty Room F09

Session chair: Gábor Kertész

32	István Finta, Gergely Éliás and János Illés	Packet Loss and Duplication Handling in Stream Processing Environment
20	László Molnár, <u>József Domokos</u> , Ferando Isabella and István Módy	Establishing sleep stages using Delta, Theta and Gamma oscillations from long term Local Field Potential (LFP) recordings in mice
40	Eva Beke, Antal Bódi, Tibor Kovács, Dóra Maros, Katalin György and László Gáspár	The role of drones in linking Industry 4.0 and ITS ecosystems
7	Irina Georgescu and Jani Kinnunen	The influence of prudence and temperance on the credibilistic portfolio optimization
30	Olivér Törő, Tamás Bécsi, Szilárd Aradi and Ádám Vellai	Multimodel state estimation in road traffic using constrained filtering

9:00 – 10:40 [T1b] PhD Student Workshop on Applied Informatics in Computational Intelligence II

Room F08

Session organizer and session chair: László Horváth

44	Esmeralda Kadena and Peter Holicza	Security Issues in the Blockchain(ed) World
53	Istvan Lovas and Andras Molnar	Quadcopter power consumption analyzation at different landing trajectories

56	Róbert Pethe and Levente Kovács	Static Edge Voting Models
57	Sinan Koçak, Edit Tóth-Laufer and László Pokorádi	Comparision of the Defuzzification Methods in Risk Assessment Applications
58	Árpád Varga, György Eigner and József Tar	Simple aeromechanical test bed for preliminary performance evaluation of robust nonlinear control methods
10	Philipp Rosenberger and József Tick	Suitability of PMBOK 6th edition for agile-developed IT Projects

9:00 – 10:40 **Poster session**

Room F07

Session chair: Rudolf Andoga

4	Sándor Szénási, Imre Felde, Gábor Kertész and László Nádai	Comparison of Road Accident Black Spot Searching Methods
5	Sándor Szénási, Imre Felde, Gábor Kertész and László Nádai	Road Accident Black Spot Localisation using Morphological Image Processing Methods on Heatmap
25	Annamária Koncz and László Pokorádi	8D Usage in Automotive Industry
27	Éva Csilla Berecz and Gábor Kiss	Dangers in autonomous vehicles
28	László Tóth and Gábor Kiss	The Relationship Between Standard and Autonomous Vehicles
33	Tímea Lázár-Fülep	Few Words about Reliability of Vehicle Systems with Complex Interconnections
41	Ádám Pintér and Sándor Szénási	Classification of source code solutions based on the solved programming tasks
43	Marián Hudák, Štefan Korečko , Branislav Sobota, Tomáš Balluch and Jakub Grib	Walking Pad and Gyroscope-Based Object Manipulation for Virtual Reality CAVE
47	Alen Hatibovic and Péter Kádár	The application of autonomous drones in the environment of overhead lines
55	Claudia-Adina Bojan-Dragos, Radu-Emil Precup, Elena-Lorena Hedrea, Attila Simo and Alexandra Daia	Discrete time Control Solutions for Inverted Pendulum Crane Mode Control
62	Rudolf Andoga, Michal Schreiner, Tomáš Moravec, Ladislav Főző and Martin Schrötter	Automatic decision making process in a small unmanned airplane

10:40 – 11:00 Coffee break

11:00 – 12:20 **Special session on 'Safety and Reliability of Vehicles Systems'**

Room F09

Session organizer and session chair: László Pokorádi

11	Dániel András Drexler, Árpád Takács, Péter Galambos, Imre J. Rudas and Tamás Haidegger	Handover process models of autonomous cars up to level 3 autonomy
35	István Nagy and Szilárd Tuloki	Fault Analysis and System Modelling in Vehicle Engineering
49	Árpád Barsi, Ádám Nyerges, Vivien Potó, Szilveszter Siroki, Viktor Tihanyi and Márton Virt	Offline path planning of automated vehicles for slow speed maneuvering
24	László Pokorádi	Methodology of Advanced Graph Model-based Vehichle Systems' Analysis

12:20 – 14:00 Lunch

I. Results of the ERC Tamed Cancer StG Grant (679681)

Session chair: Levente Kovács

14.00-14.20 - Tamed Cancer: Results and perspectives

- Levente Kovács, Principal Investigator, Physiological Controls Research Center, Óbuda University

14.20-10.35 – Control-oriented modeling of tumorous angiogenesis and tumor growth

- Dávid Csercsik, post-doc, Physiological Controls Research Center, Óbuda University

14.35-14.50 - Qualitative analysis of a closed-loop model of tumor growth control

- Dániel András Drexler, post-doc, Physiological Controls Research Center, Óbuda University

17	Dániel András Drexler, Ilona Nagy, Valery Romanovski, János Tóth and Levente Kovács	Qualitative analysis of a closed-loop model of tumor growth control
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14.50-15.05 – Tumor growth control by using TP-LPV-LMI methodologies

- György Eigner, post-doc, Physiological Controls Research Center, Óbuda University

15.05-15.15 – Robust and optimal control of tumor growth

- Bence Czakó, PhD student, Physiological Controls Research Center, Óbuda University

15.15-15.25 - Spatio-temporal modeling of tumor progression

- Tamás Gönczy, MSc student, Physiological Controls Research Center, Óbuda University

15.25-15.45 Coffee Break**II. International experts**

Session chair: Levente Kovács

15.45-16.05 – Modeling Haemorrhagic Shock

- Andrea de Gaetano, CNR IASI BioMatLab, Rome, Italy

16.05-16.25 – Emerging research topics for Control 4.0: a Ghent University -DYSC perspective

- Clara Ionescu, Ghent University, Belgium

16.25-16.45 – Control engineering approach in anesthesia: results of UNIBS

- Antonio Valsioli, University of Brescia, Italy

16.45-17.00 – Machine learning in biochemistry and medicine

- Eva Dulf, Technical University Cluj-Napoca, Romania