Distributed Coordination and Learning on Multi-Agent Systems

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This talk will provide an overview of the latest developments in distributed coordinated control and learning techniques for multi-agent systems (MAS). As an increasingly popular research area, MAS has the potential to revolutionize various industries, such as robotics, transportation, and manufacturing, by enabling a group of agents to autonomously work together to achieve complex objectives. During the presentation, we will discuss the recent advances in robust, resilient, and safe coordinated control of MAS under constraints such as uncertainties, disturbances, cyberattacks, and dynamic environments. Additionally, we will explore how machine learning techniques, particularly reinforcement learning, have been employed to enable agents to learn and adapt in real-time, uncertain, and dynamic environments. Examples of MAS applications in multiple autonomous systems, heterogenous systems, and human-machine systems are also provided. Finally, we will touch upon some of the current challenges and future research directions in MAS, including the integration of human-agent interaction, and the development of theoretical frameworks to better understand the underlying dynamics of these complex systems.



Peng Shi received the PhD degree in Electrical Engineering from the University of Newcastle, Australia, the PhD degree in Mathematics from the University of South Australia, the Doctor of Science degree from the University of Glamorgan, UK, and the Doctor of Engineering degree from the University of Adelaide, Australia. He is now a Professor at the School of Electrical and Mechanical Engineering, and the Director of Advanced Unmanned Systems Laboratory, at the University of Adelaide, Australia. His research interests include systems and control theory and applications to autonomous and robotic systems, cyber-physical systems, and multi-agent systems. He received the Ramesh Agarwal Life-time Achievement

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