



ÓBUDAI EGYETEM  
ÓBUDA UNIVERSITY

IEEE  
23<sup>rd</sup> International  
Symposium on  
Computational  
Intelligence and  
Informatics  
(IEEE CINTI 2023)

# Evolutionary Computation for Intelligent Data Analytics

## Key Applications in Engineering

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UTS CRICOS 00099F

# AI in Action – An overview

## What is Artificial Intelligence (AI) ?

**AI: The ability of a machine to perform cognitive functions we associate with human minds, such as perceiving, reasoning, learning**

Exponential increases in computing power and storage

1965: Moore's law

Explosion of data

1991: Opening of the World Wide Web

1805: Legendre lays the ground work for machine learning

Algorithmic advancements

2011: IBM Watson beats Jeopardy

2014: Number of mobile devices exceeds number of humans

2009: Ng uses GPUs to train deep learning models more efficiently

2012: Google demonstrate effectiveness of deep learning for image recognition

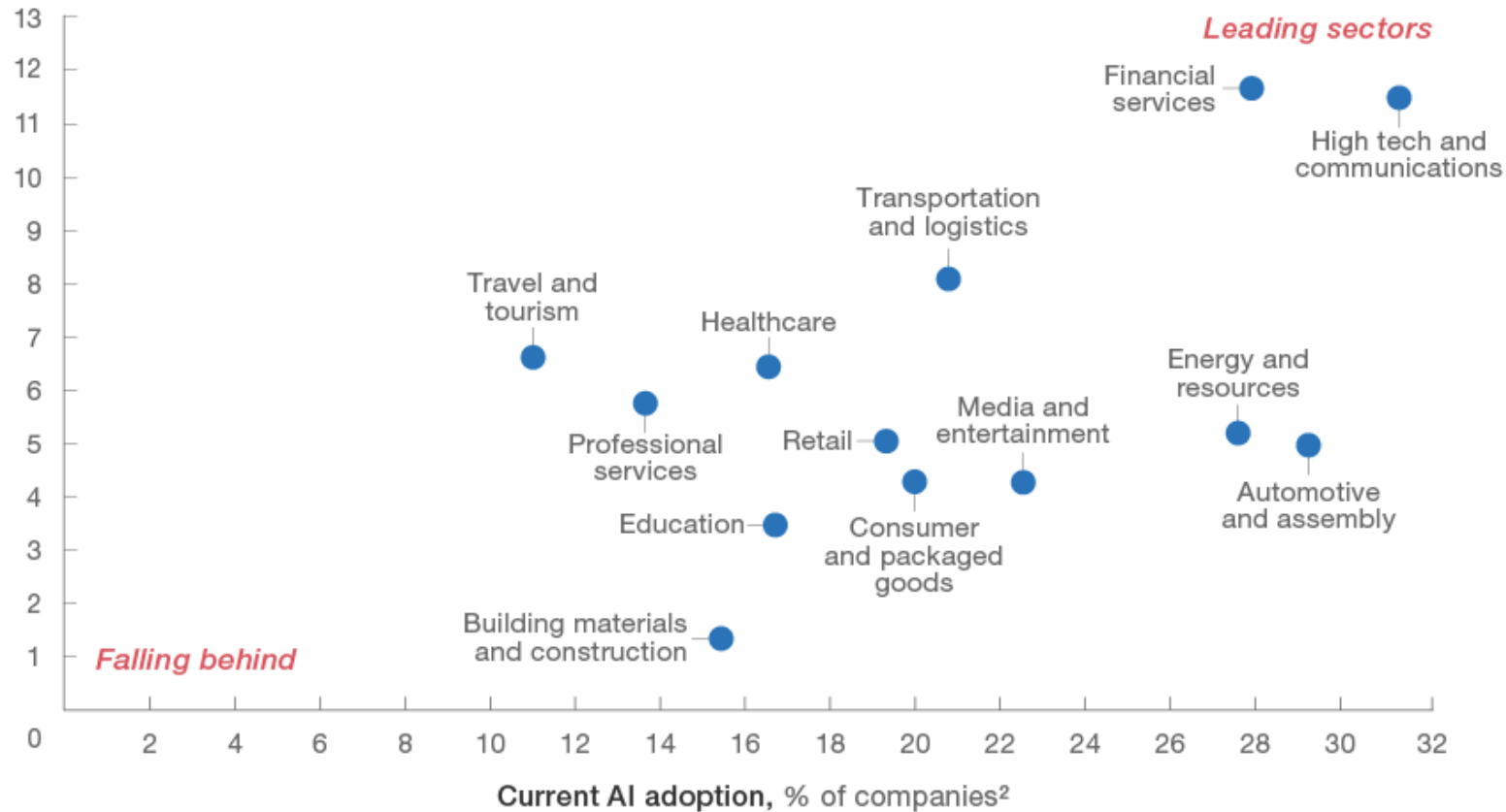
2017: AlphaZero beats AlphaGo Zero

2022: ChatGPT

**A convergence of algorithmic advances, data proliferation, and tremendous increases in computing power and storage has propelled AI from hype to reality**

Leaders in the adoption of artificial intelligence also intend to **invest more in the near future** compared with laggards.

Future artificial intelligence (AI)-demand trajectory, % change in AI spending over next 3 years<sup>1</sup>

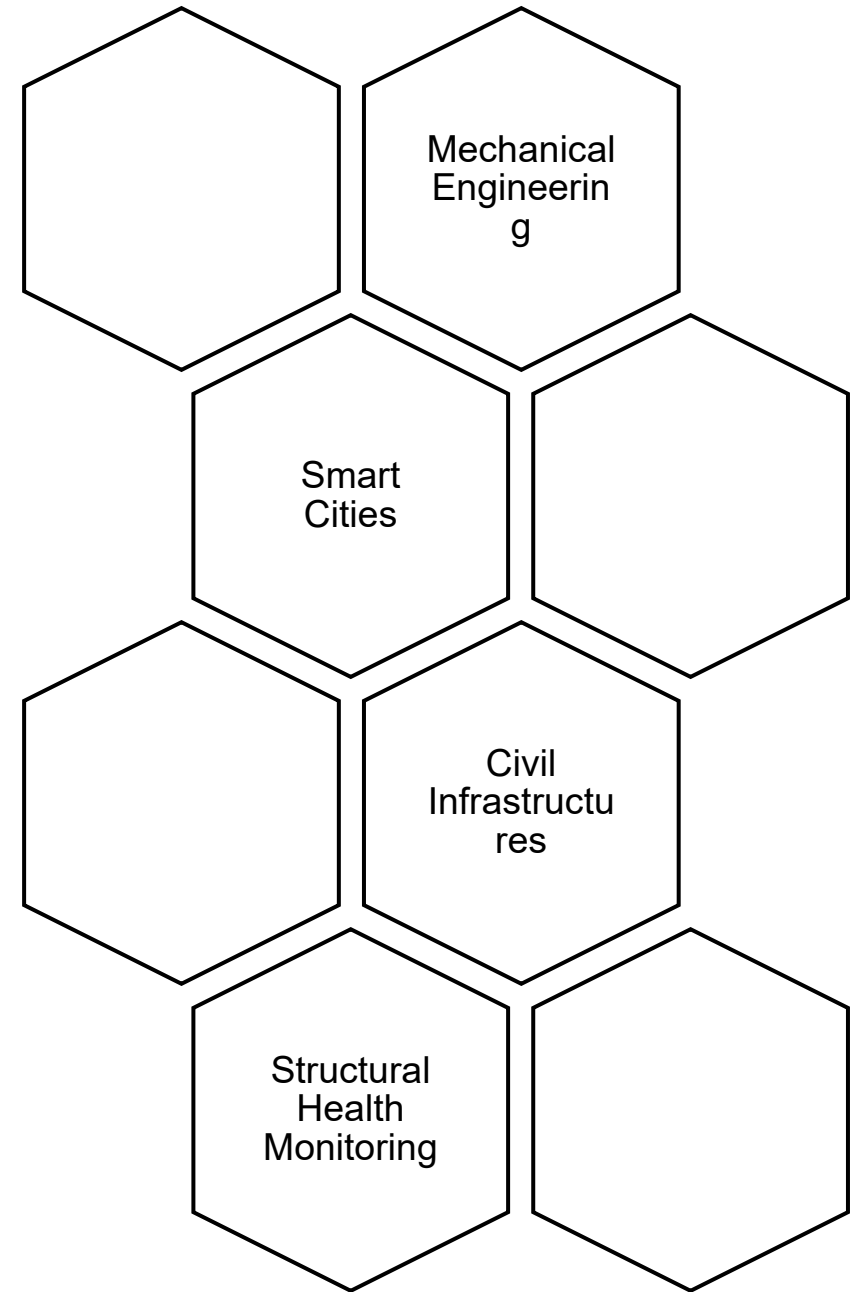
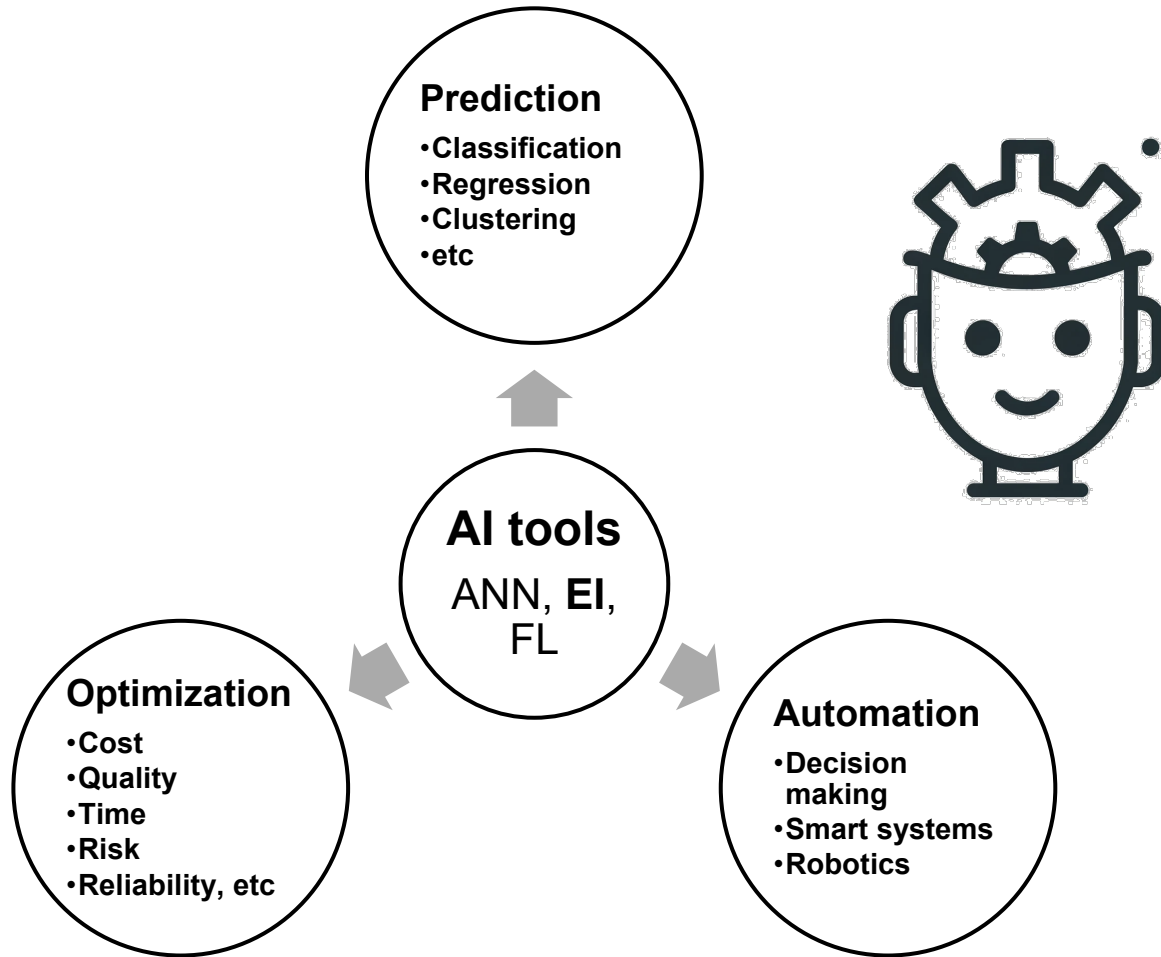


<sup>1</sup>Estimated average, weighted by company size; demand trajectory based on midpoint of range selected by survey respondent.

<sup>2</sup>Adopting 1 or more AI technologies at scale or in business core; weighted by company size.

Source: McKinsey Global Institute AI adoption and use survey; McKinsey Global Institute analysis

# How we use AI in Action



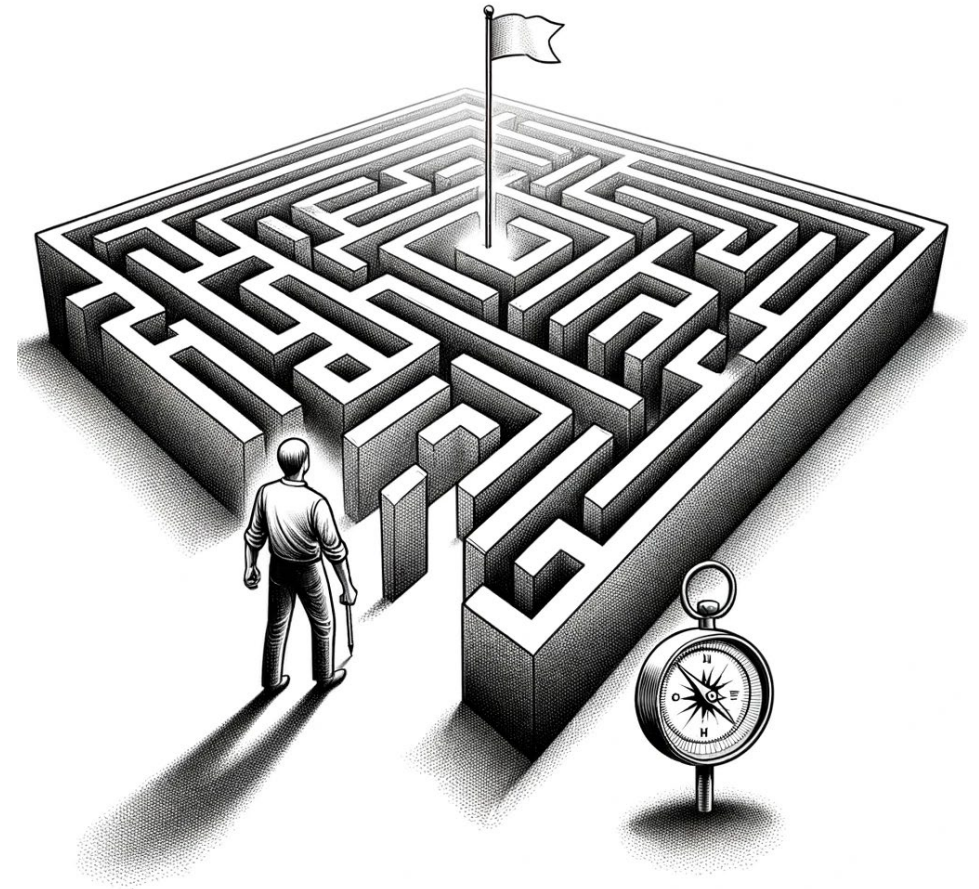
# Evolutionary Intelligence in Engineering

## Outlines

Modelling

Optimization

Monitoring

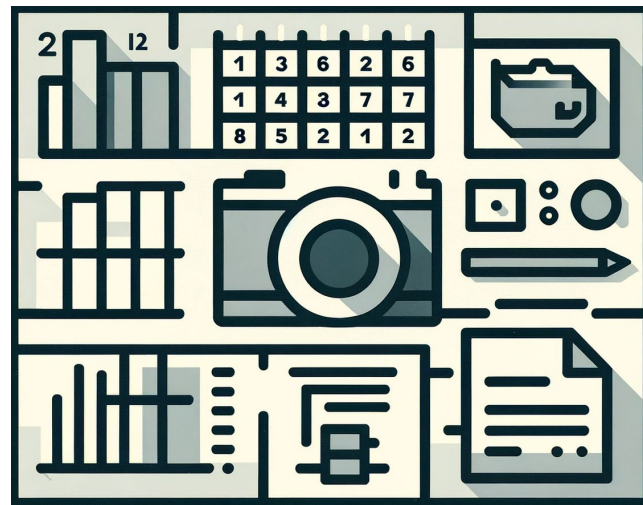


# AI/EI for Engineering Modelling



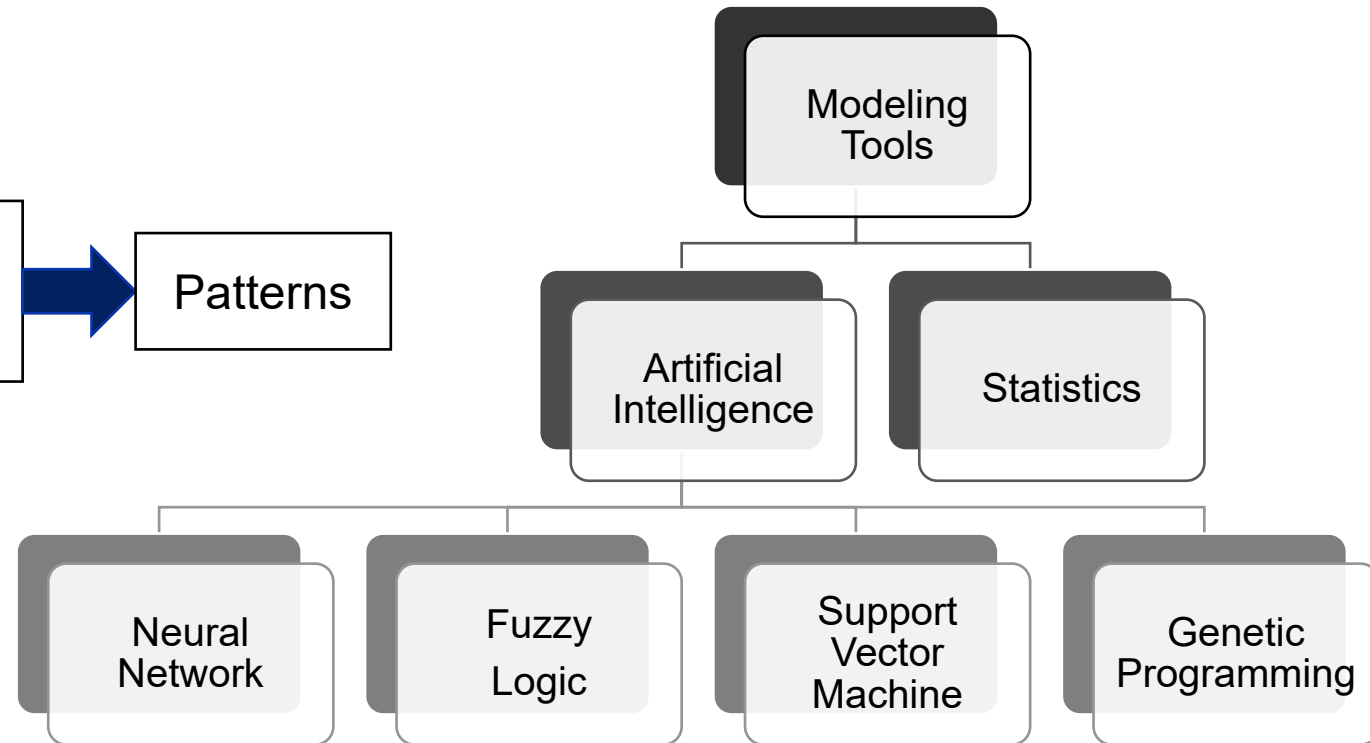
# AI-based Data-Driven based Modelling Tools

➔ Discovering patterns

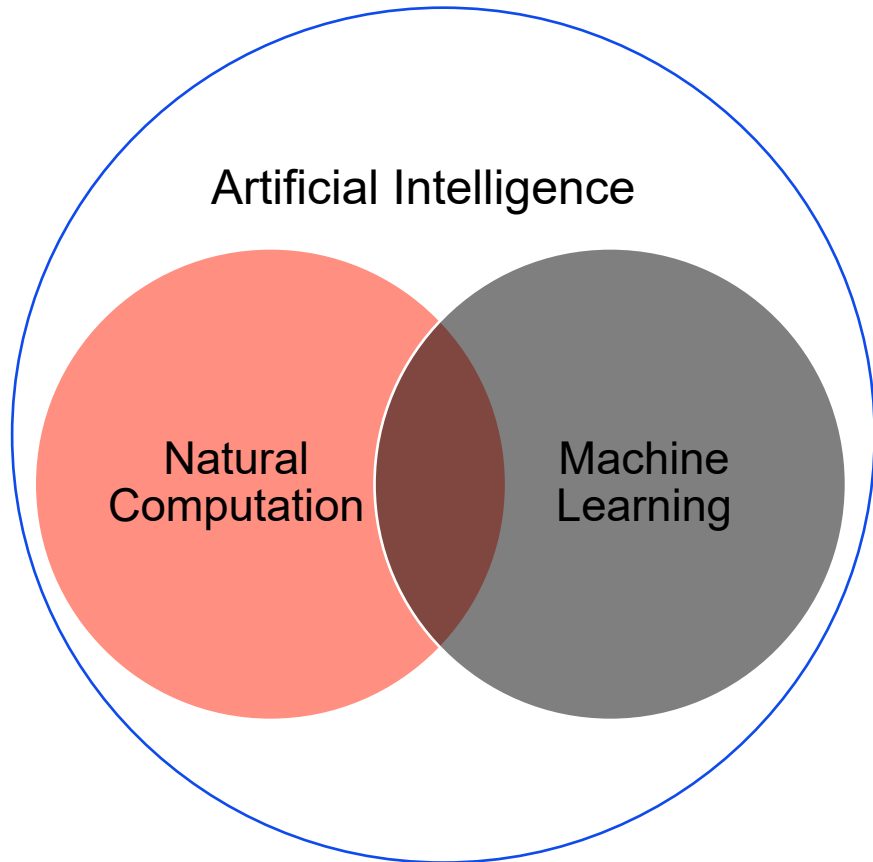


Data Mining

Patterns



# AI-based Predictive Data Analytic Tools



Look deep into nature, and then you will understand everything better

**Albert Einstein**

Nature is the source of all true knowledge.

**Leonardo da Vinci**

Telikani A., Tahmassebi, A.H., Banzhaf, W., Gandomi, A.H.\*, "Evolutionary Machine Learning: A Survey" ACM Computing Surveys, ACM, 54(8), 11-50, 2021.





# Evolution

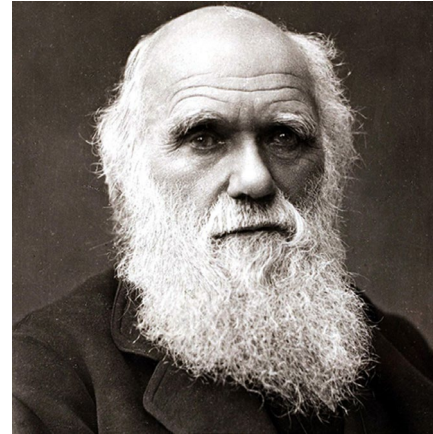


## Evolution Philosophy

Jalal-Din M. Rumi (Mevlâna)

13<sup>th</sup> Century

“I died as a mineral and became a plant,  
I died as plant and rose to animal,  
I died as animal and I was Man.”



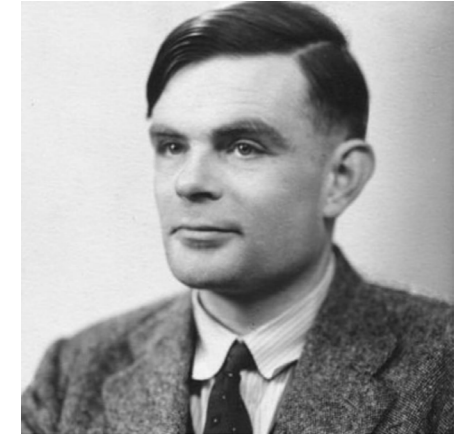
## Theory of Evolution

**based on Natural Selection**

Charles R. Darwin

1859

“On the Origin of Species”



## Evolutionary Search & Learning

Alan M. Turing

1950

“...there is the genetic or evolutionary search by which a combination of genes is looked for, the criterion being the survival value”

# What is Genetic Programming

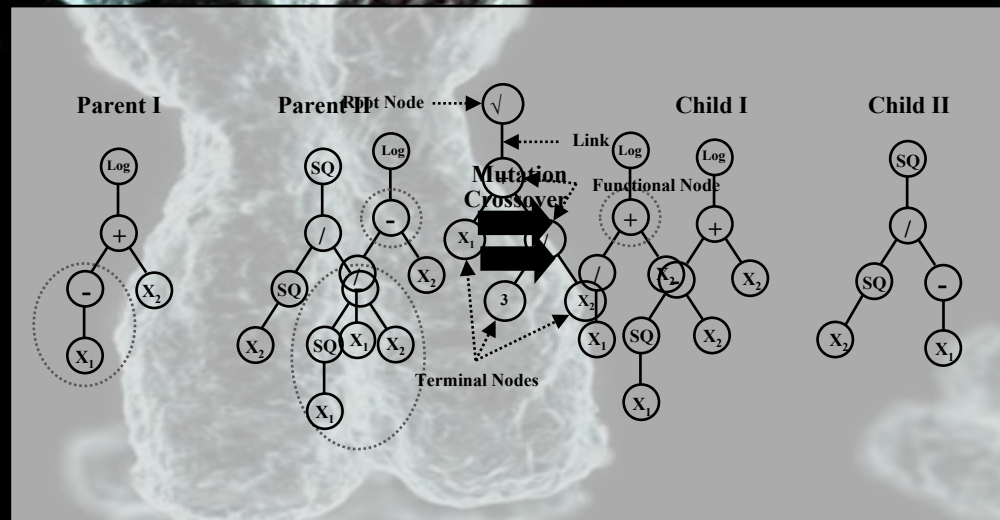
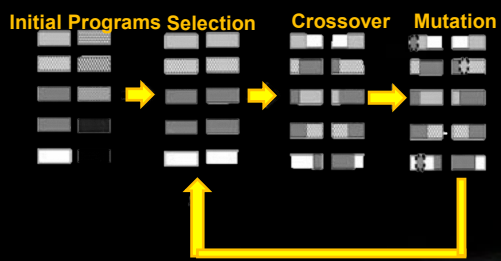
## A Software with Evolution as the programmer!

- Many problems can be solved by genetic programming!
- Most popular for predictive data analytics

Reference:

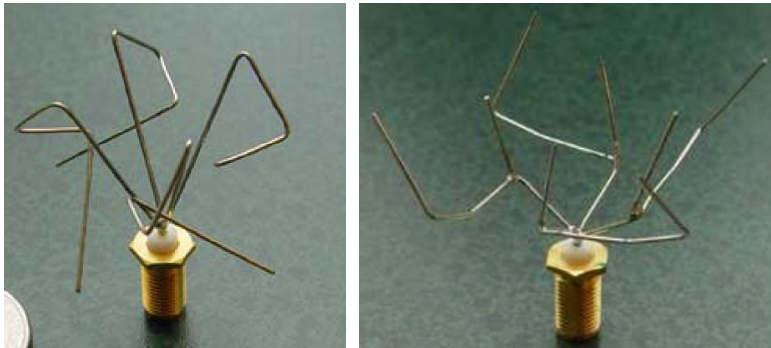
Gandomi, Amir H., et al. *Handbook of genetic programming applications*. Cham: Springer, 2015.





# Finding the Model Structure

NASA Communication antennas  
On the ST-5 mission (2006)

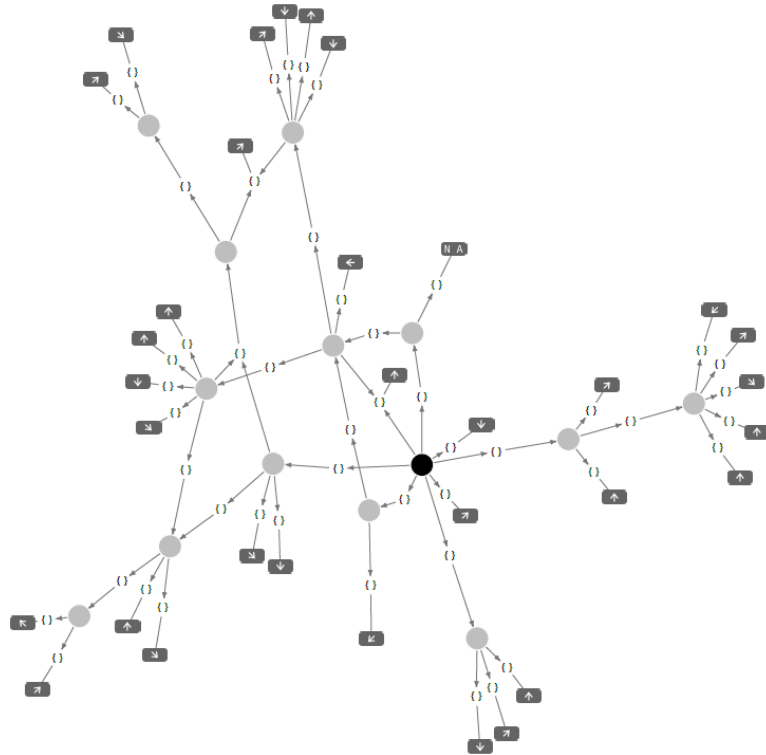


Jason D. Lohn, Gregory S. Hornby and Derek S. Linden,  
“Human-competitive evolved antennas”, *Artificial Intelligence  
for Engineering Design, Analysis and Manufacturing*, volume  
22, issue 3, pages 235–247 (2008).

In Genetic Programming:

- The Structure is found via Evolution
- Pre-defined structure is not required
- Distinguished feature from other machine learning methods
- It can model the behaviour without any prior assumptions

# Simplicity and Explainability



Kelly, Stephen, and Malcolm I. Heywood. "Emergent tangled graph representations for Atari game playing agents." In European Conference on Genetic Programming, pp. 64-79. Springer, Cham, 2017.

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Intelligent Machines

## Evolutionary algorithm outperforms deep-learning machines at video games

Neural networks have garnered all the headlines, but a much more powerful approach is waiting in the wings.

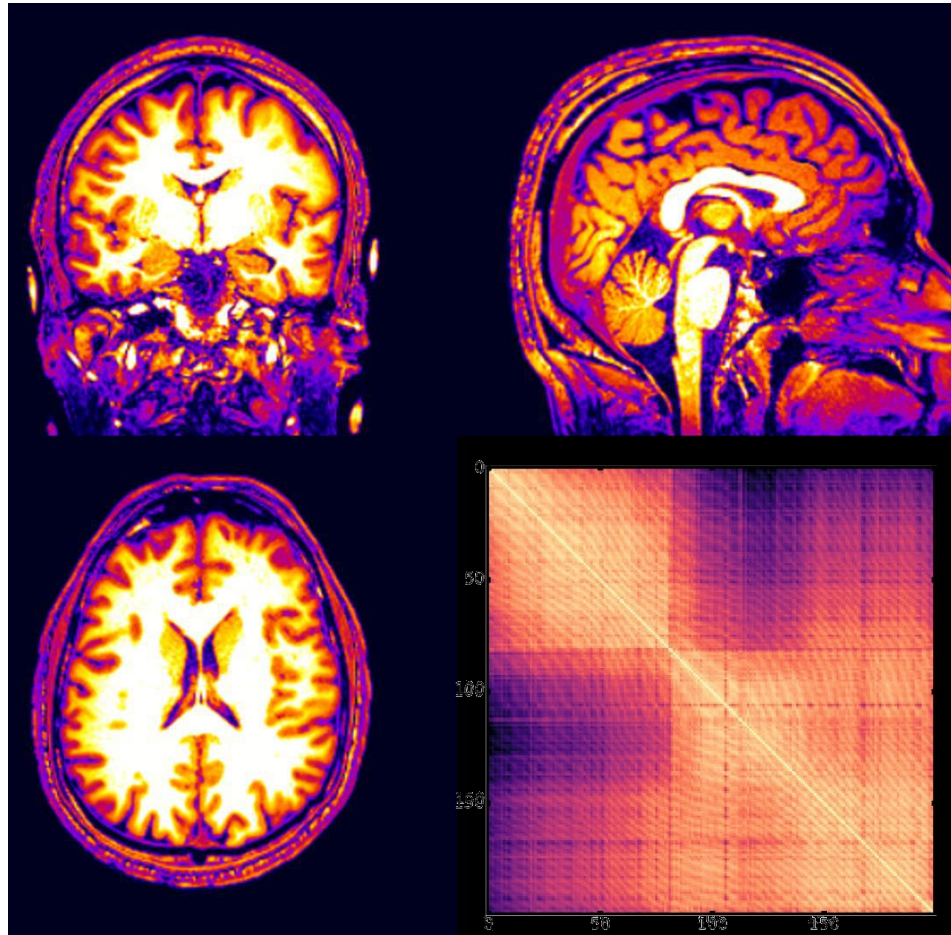
by Emerging Technology from the arXiv July 18, 2018

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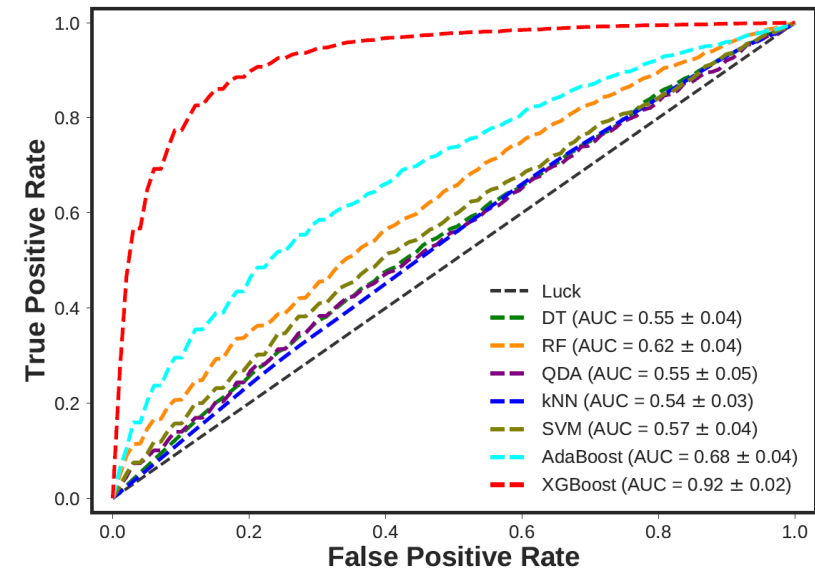
**With all the excitement over neural networks and deep-learning**

Wilson, D. G., Cussat-Blanc, S., Luga, H., and Miller, J. F. Evolving simple programs for playing atari games. In Proceedings of the Genetic and Evolutionary Computation Conference. ACM, (2018).

# Inherently Making the Selections!

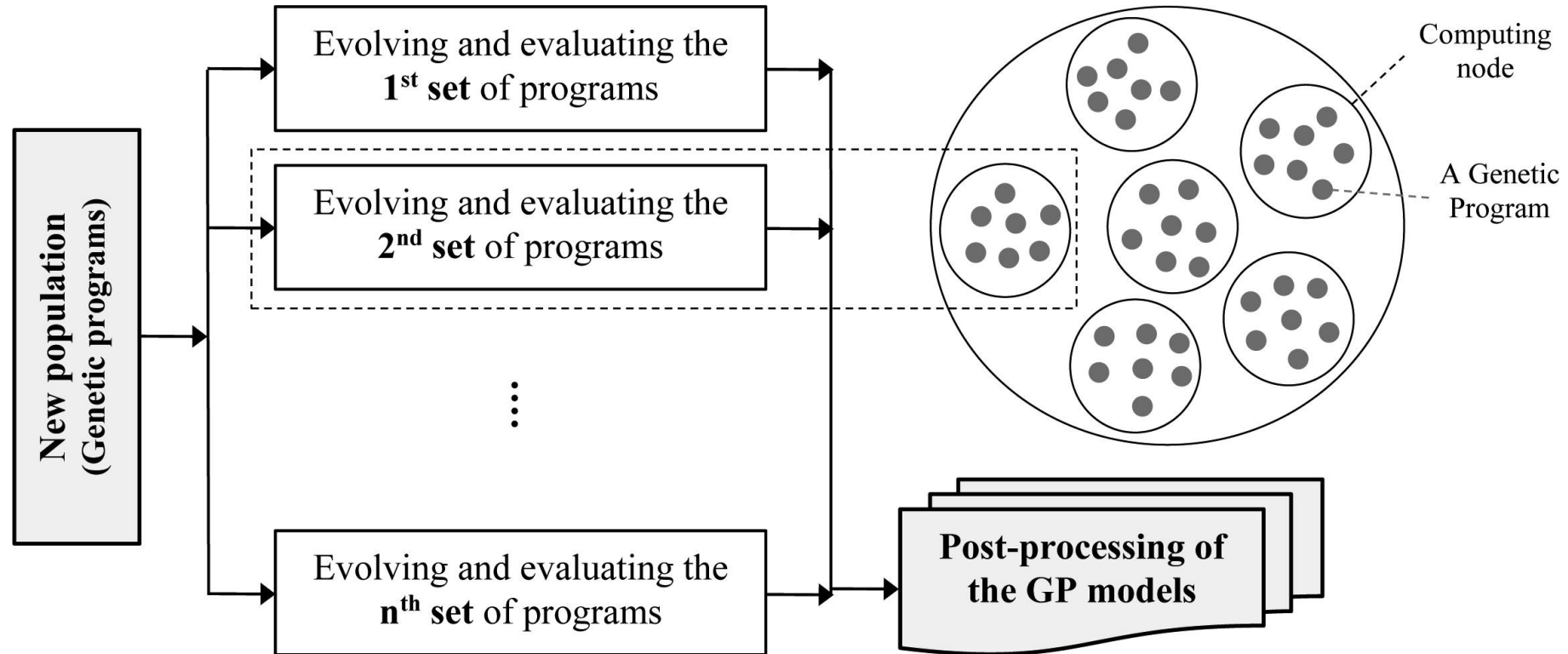


After cleaning data  
Feature selection  
Model selection



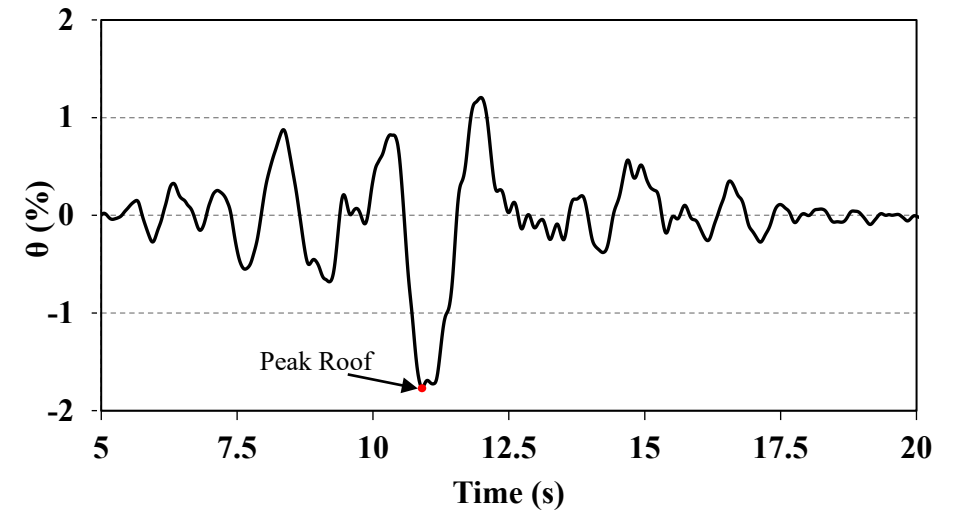
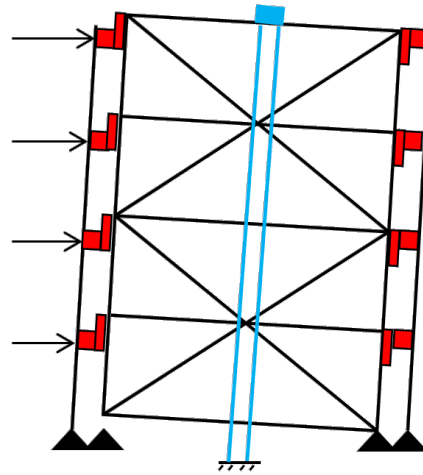
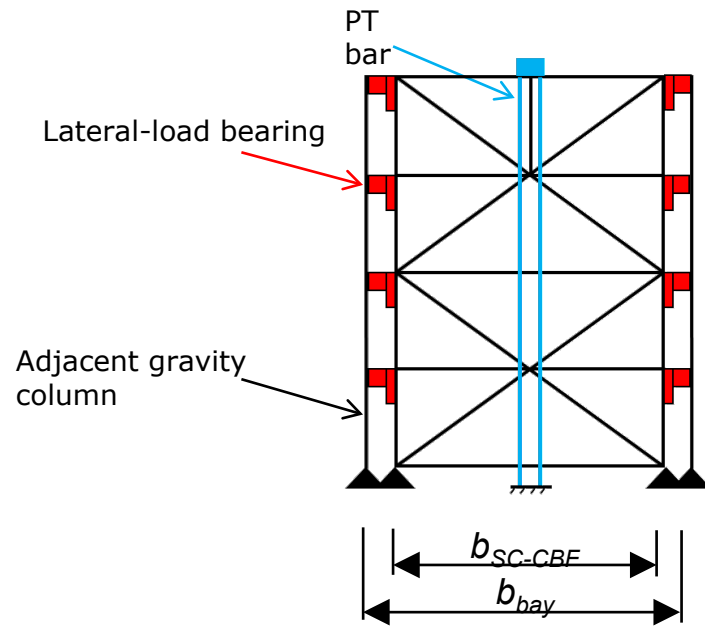
Tahmassebi, A. Gandomi A.H., et al. (2018) "Optimized Naive Bayes and Decision Tree Big Data Analysis for Stroke Lesion Classification" Proceedings Wiley. PEARC18, ACM.

# Parallel Processing in Genetic Programming



Gharehbaghi, S., Gandomi, M., Plevris, V. and Gandomi, A.H., 2021. Prediction of seismic damage spectra using computational intelligence methods. Computers & Structures, 253, p.106584.

# Ex. I.1: Response of Self-Centering Concentrically Braced Frames



Gandomi A.H., "Seismic Response Formulation of Self-Centering Concentrically Braced Frames Using Genetic Programming" 2014 IEEE Symposium on Computational Intelligence, Orlando, FL, December 9-12, 2014.



# Ex. I.1: Formulation of each Record's Response

$$\theta = f(\text{Structural Design}, \text{Intensity Measures})$$

**Intensity Measures:**

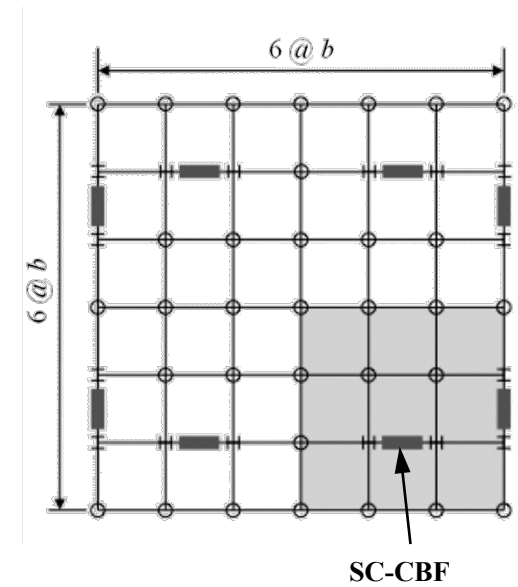
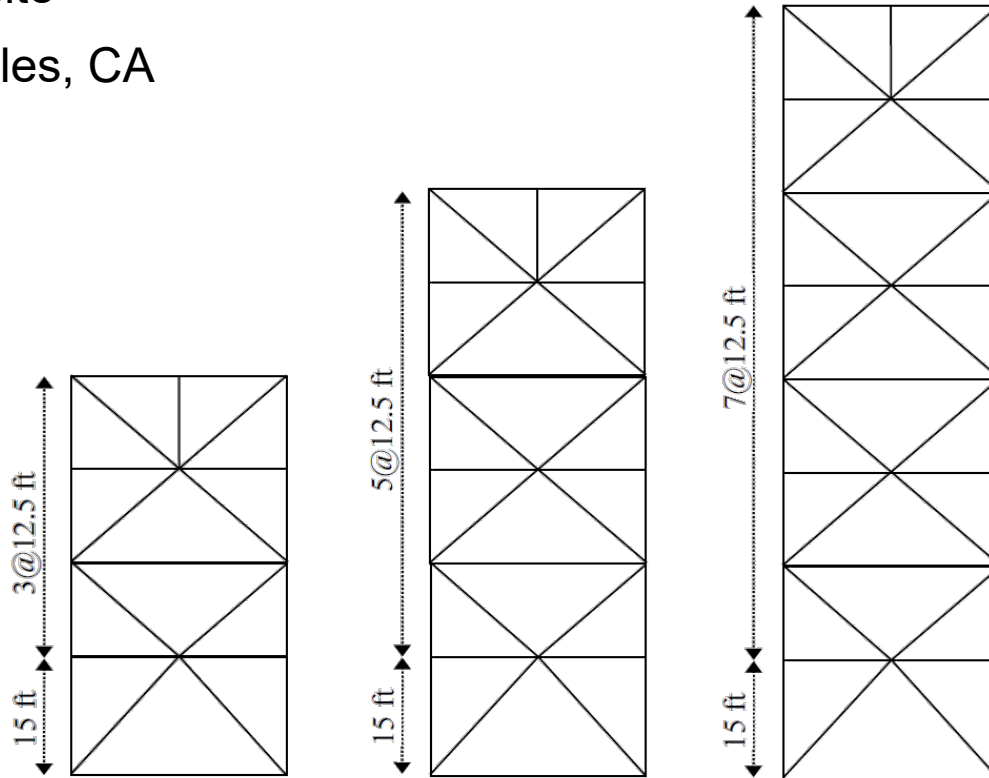
IM
Elastic spectral acceleration
Elastic spectral acceleration
Elastic spectral velocity
Elastic spectral displacement
Peak ground acceleration
Peak ground velocity
Peak ground displacement
Cumulative absolute velocity
Cumulative absolute displacement
Arias intensity
Velocity intensity
Root mean square acceleration
Characteristic intensity
Strong ground motion duration

**Structural Design:**

Geometrical		Mechanical	
$b, ft (m)$	$h, ft (m)$	$F_y, ksi (MPa)$	$\mu$
22.5 (6.9)	52.5 (16)	36 (248)	0.30
30 (9.1)	77.5 (23.6)	50 (345)	0.45
40 (12.2)	102.5 (31.2)	60 (414)	0.60

# SC-CBF Parameters

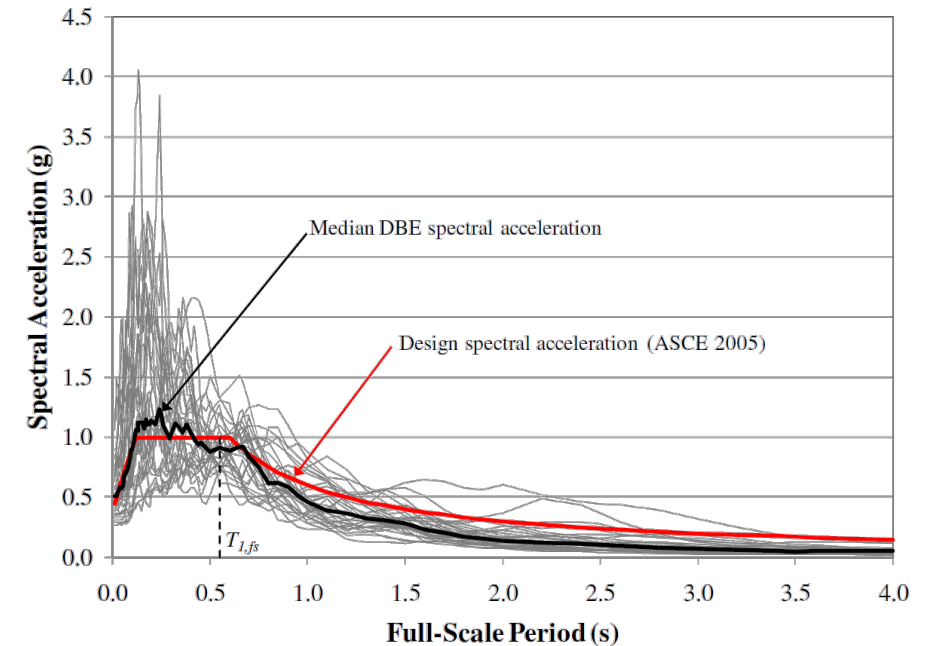
Office buildings  
Stiff soil site  
Los Angeles, CA



# Nonlinear Dynamic Analysis

- 1) 75 SC-CBF System are designed
- 2) 30 earthquake records in DBE level
- 3) 140 ground motion records used in the FEMA SAC Steel Project

Area	FOE	DBE	MCE
Los Angeles, CA	20	20	20
Boston, MA	X	20	20
Seattle, WA	X	20	20



# Feature Selection: Evolutionary Coefficient

- Best correlation coefficient (R)!
- R: linear relationship

$$R_e = \frac{\sum_{i=1}^n (y_i - \bar{y}_i) \left( f_{j,GP}(x_{ij}) - \overline{f_{j,GP}(x_{ij})} \right)}{\sqrt{\sum_{i=1}^n (y_i - \bar{y}_i)^2 \sum_{i=1}^n \left( f_{j,GP}(x_{ij}) - \overline{f_{j,GP}(x_{ij})} \right)^2}}$$

- $f_{j,GP}$ : Transformed and correlated  $x_j$

Gandomi A.H., "Seismic Response Formulation of Self-Centering Concentrically Braced Frames Using Genetic Programming" 2014 IEEE Symposium on Computational Intelligence, Orlando, FL, December 9-12, 2014.

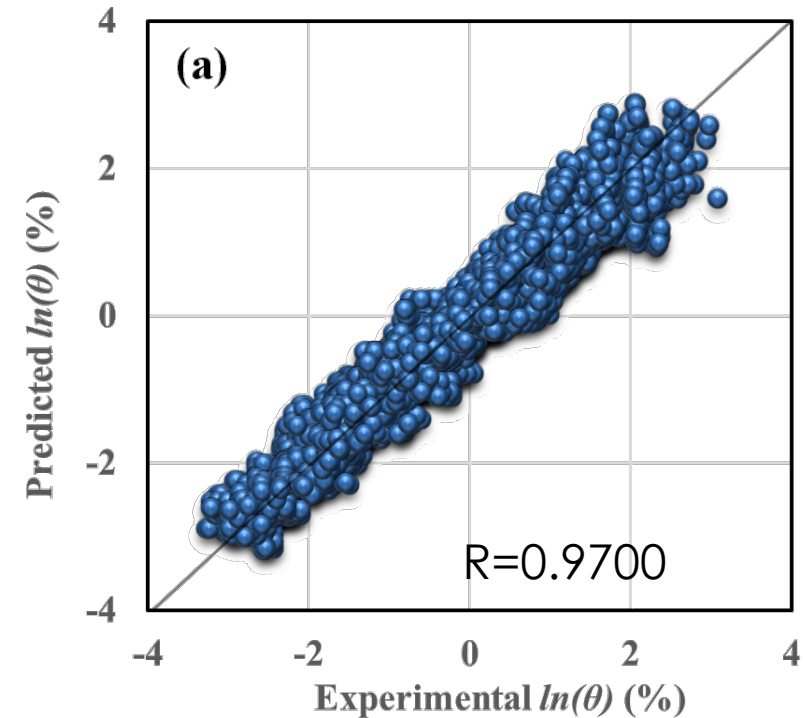
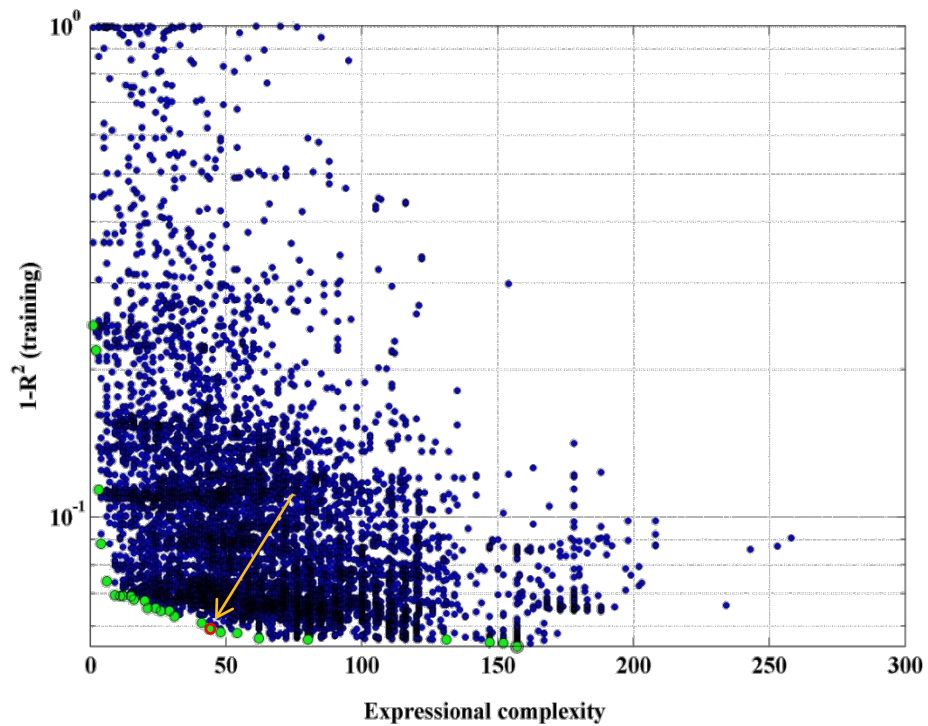
# Feature Selection: Evolutionary Coefficient

IM	Symbol	$R^2$	$R_e^2$	$\uparrow$ (%)	Rank
Elastic spectral acceleration	$S_a(T)$	0.5589	0.7975	42.7	3
Elastic spectral acceleration	$S_a(2T)$	0.6709	0.8680	29.4	2
Elastic spectral velocity	$S_v$	0.5560	0.7938	42.8	4
Elastic spectral displacement	$S_d$	0.5147	0.7761	50.8	5
Peak ground acceleration	PGA	0.4190	0.5359	27.9	10
Peak ground velocity	PGV	0.7765	0.9022	16.2	1
Peak ground displacement	PGD	0.5181	0.7222	39.4	6
Cumulative absolute velocity	CAV	0.1890	0.5694	201.3	11
Cumulative absolute displacement	CAD	0.4036	0.6729	66.7	7
Arias intensity	$I_A$	0.1461	0.6612	352.6	8
Velocity intensity	$I_v$	0.4233	0.6454	52.5	9
Root mean square acceleration	$A_{rms}$	0.2858	0.3235	13.2	13
Characteristic intensity	$I_c$	0.2053	0.3305	61.0	12
Strong ground motion duration	$T_D$	0.0216	0.0881	307.9	14

# Formulation of each Record's Response

## Multi-Objective Strategy

$$\ln(\theta) = 25.9PGV + 0.615 \ln \left| \tanh(2S_a(T)) \left( S_a(2T) + \left( \frac{h}{b} \right)^2 \right) \sqrt{F_y} \right| - 1.08$$

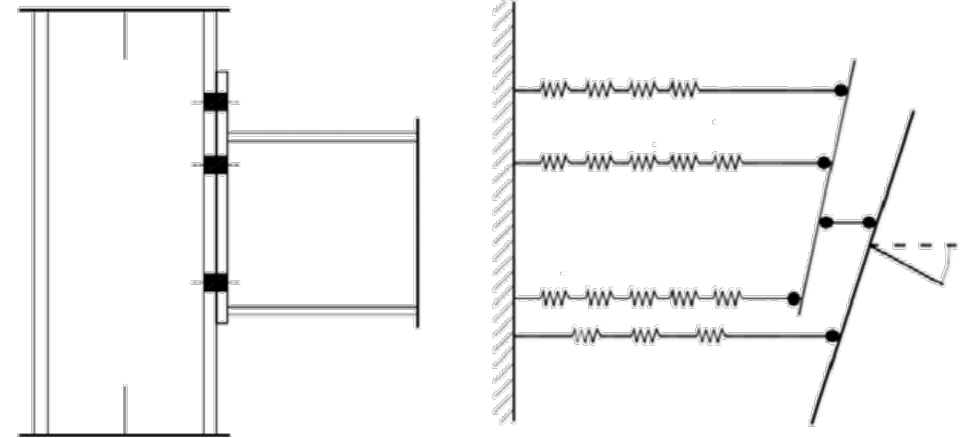


Gandomi, Amir H., and David Roke. "A Multi-Objective Evolutionary Framework for Formulation of Nonlinear Structural Systems." *IEEE Transactions on Industrial Informatics*, 18 (9), 5795 – 5803, 2022.

# Team Solution: Steel Semi-Rigid Joints

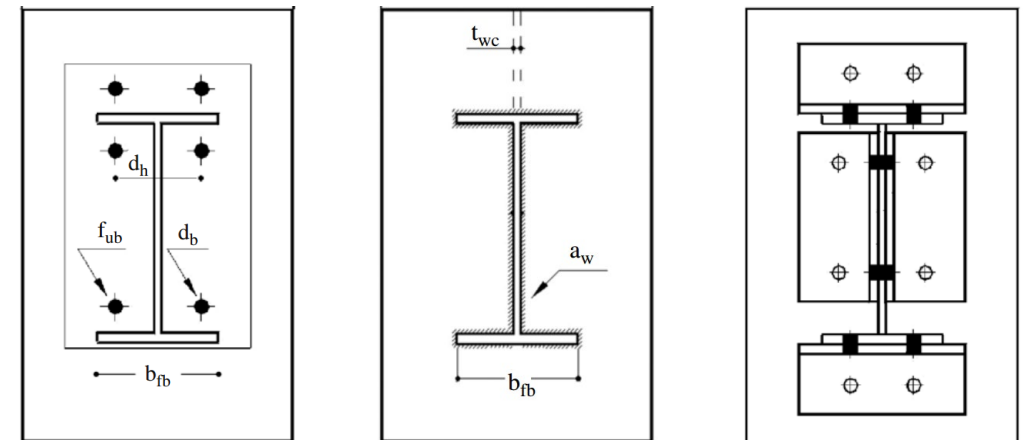
## Prediction

flexural resistance  
initial rotation stiffness



## Joint types

Extended endplate joint  
Welded joint  
Bolted angle joint



# Team GP Solution

Performance statistics of models for flexural resistance prediction for all element test data

Type of Joint	LGP (single solution)				LGP (team solution)				EC3				GP/SA		
	R	MAE	MSE		R	MAE	MSE		R	MAE	MSE		R	MAE	MSE
<b>Bolted Endplate Joint</b>	<b>0.9986</b>	8.5496	<b>123.68</b>		0.9975	<b>5.9564</b>	183.88		0.9604	29.516	3019.2		0.9793	15.45	2035.1
<b>Welded Joint</b>	0.9819	22.06	1073.5		<b>0.988</b>	<b>18.55</b>	<b>674.77</b>		0.9169	54.09	6636.1		0.9761	20.75	1333.6
<b>Bolted Joints with Angles</b>	0.9918	3.2328	25.82		<b>0.9964</b>	<b>2.6267</b>	<b>12.72</b>		0.964	11.85	193.69		0.9846	4.56	46.7

Performance statistics of models for initial rotation stiffness prediction for all element test data

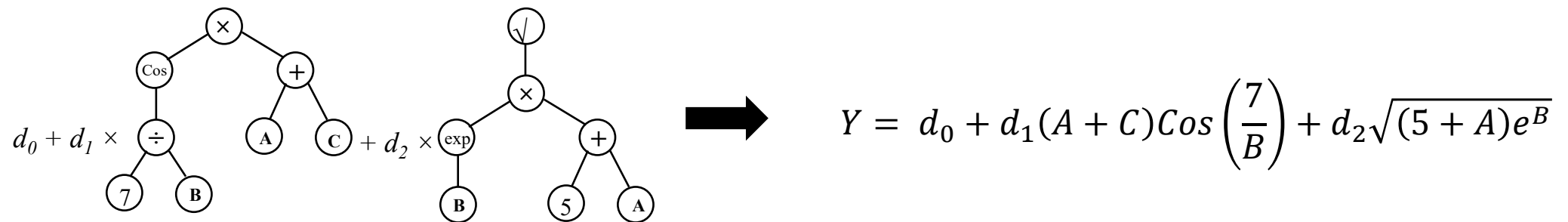
Type of Joint	LGP (single solution)				LGP (team solution)				EC3				GP/SA		
	R	MAE	MSE		R	MAE	MSE		R	MAE	MSE		R	MAE	MSE
<b>Bolted Endplate Joint</b>	0.9969	3.2788	59.11		<b>0.9985</b>	<b>2.041</b>	<b>29.28</b>		0.9778	17.041	663.42		0.9836	3.62	313.51
<b>Welded Joint</b>	0.9734	9.9467	201.14		<b>0.9735</b>	<b>9.347</b>	<b>165.04</b>		0.9455	32.36	2340.9		0.949	10.25	314.09
<b>Bolted Joints with Angles</b>	0.9901	1.88	5.5		<b>0.9923</b>	<b>1.7272</b>	<b>4.95</b>		0.9271	6.1606	63.58		0.9784	1.31	11.7

Gandomi et al. "Behavior Appraisal of Steel Semi-Rigid Joints Using Linear Genetic Programming." *Journal of Constructional Steel Research, Elsevier*, 65: 1738-1750, 2009.

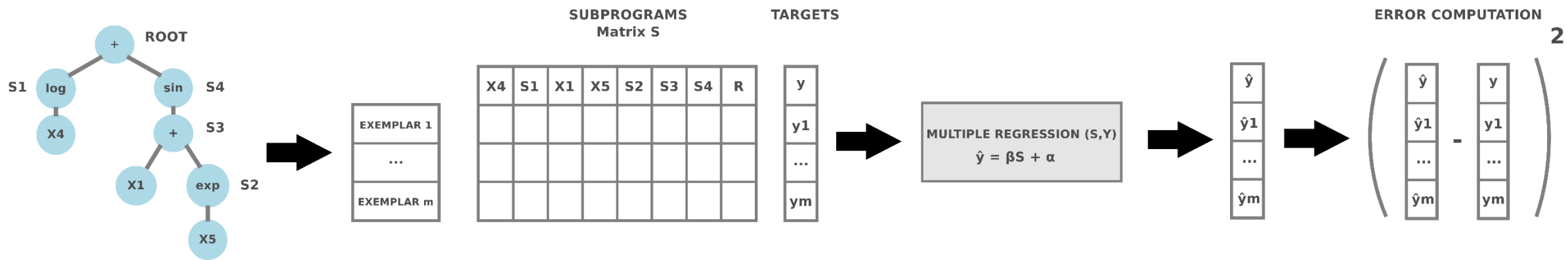


# Multiple Regression in GP

*Multi-Gene Symbolic regression (Searson et al. 2010)*



*Multiple Regression Genetic Programming (Arnaldo et al. 2014)*



# Hybrid GP for Concrete Creep Prediction

$$\hat{J}(t, t_0) = d_0 + d_1 G_1 + d_2 G_2 + d_3 G_3$$

$$G_1 = \left( \frac{w}{c} \right) \cdot \frac{\ln(t_e + 2.46)}{f'_c}$$

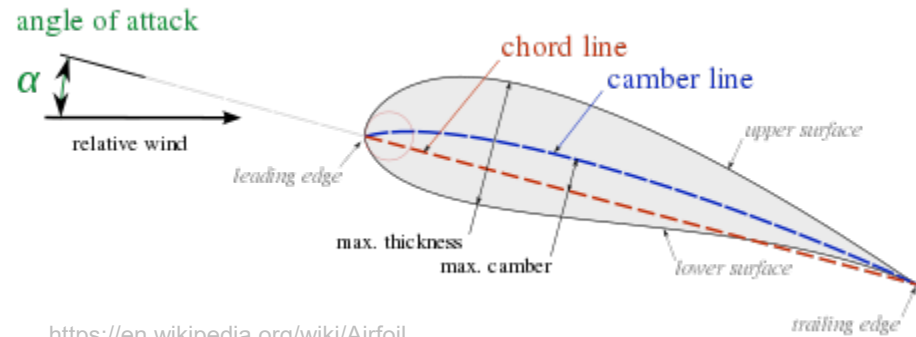
$$G_2 = \ln \left[ \left( \frac{w}{c} \right) \sqrt{t_0} \right]$$

$$G_3 = \left( \frac{f'_c \cdot t_0}{h^2} \right)^2$$

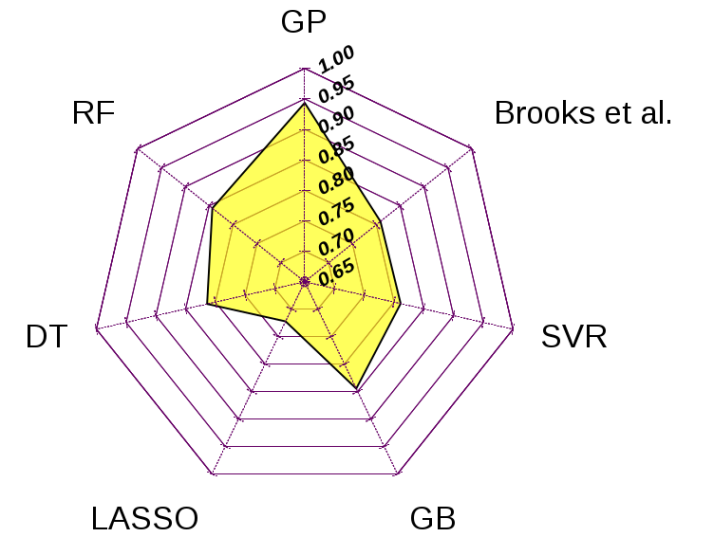
Model	Number of Variables.	Accuracy measure					
		R <sup>2</sup>	RRMS E	ρ	V <sub>CEB</sub>	F <sub>CEB</sub>	M <sub>CEB</sub>
<b>G-C</b>	5	0.83	0.37	0.19	0.37	61.7	1.63
<b>Bažant-Baweja B3</b>	10	0.56	0.62	0.35	0.59	55.7	2.10
<b>CEB-FIB MC90</b>	5	0.62	0.55	0.31	0.54	67.4	1.73
<b>GL2000</b>	6	0.48	0.69	0.41	0.65	57.9	2.22

Gandomi et al., "Genetic Programming for Experimental Big-Data Mining: A Case Study on Concrete Creep Formulation." Automation in Construction, Elsevier, 70, 89–97, 2016.

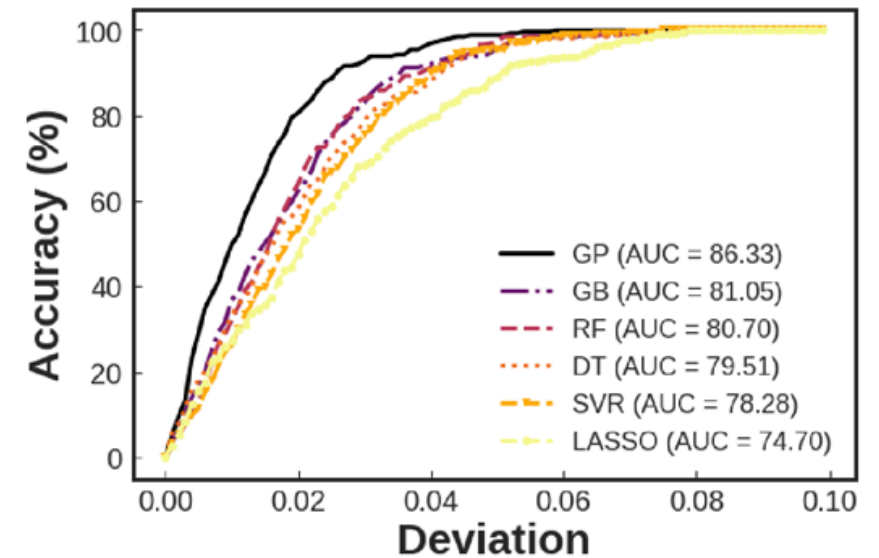
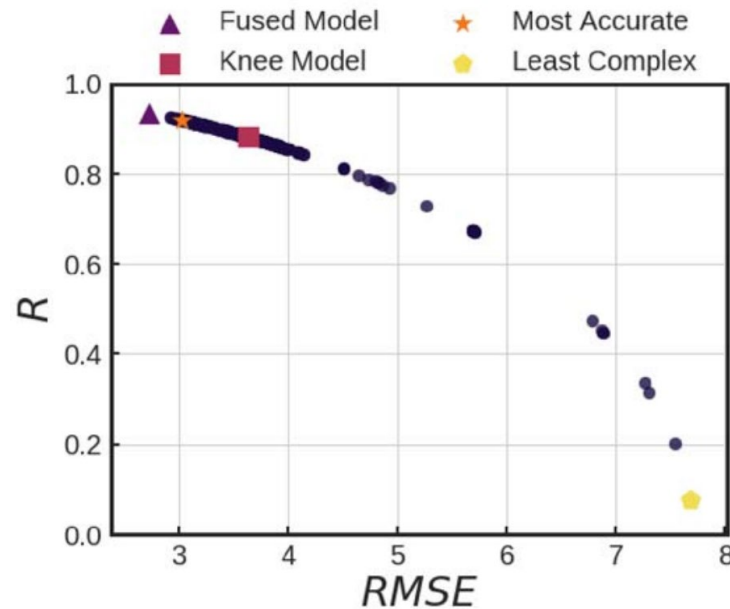
# Fused GP for Airfoil Self-Noise Prediction



<https://en.wikipedia.org/wiki/Airfoil>

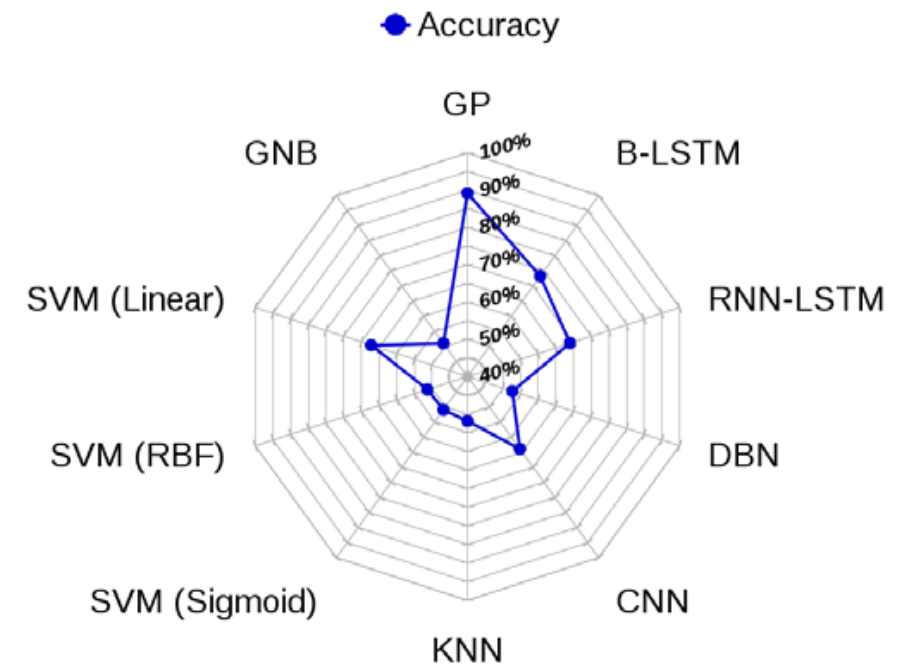
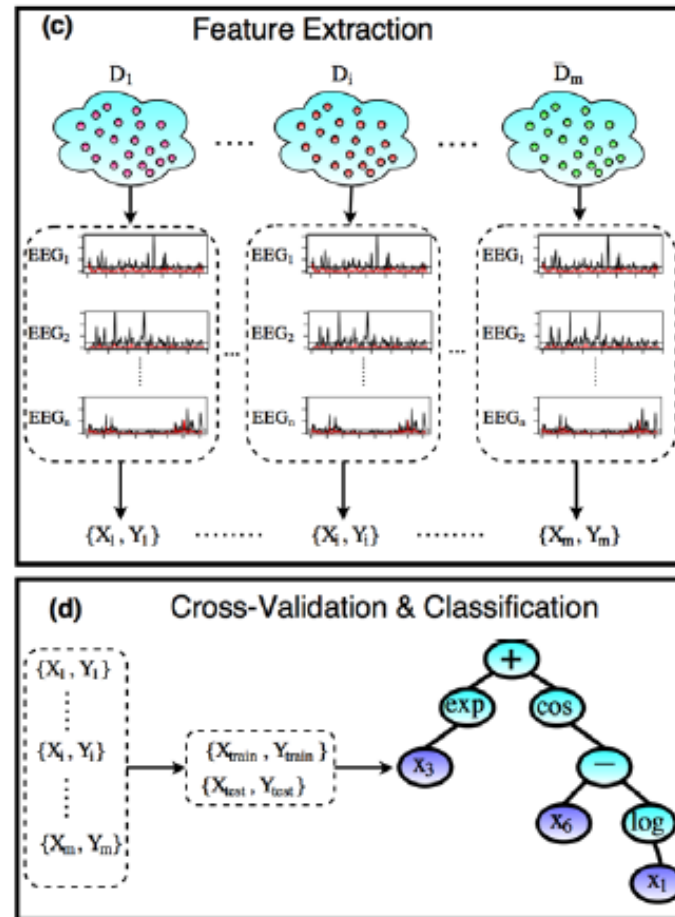
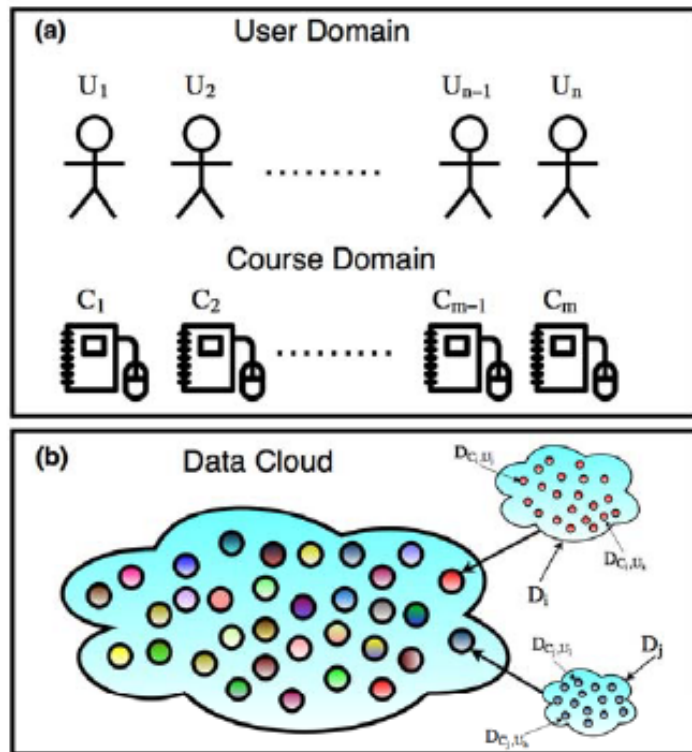


Fusing GP Models by Adaptive Regression by Mixing (ARM) Algorithm



Tahmassebi, Amirhessam, Amir H. Gandomi, and Anke Meyer-Baese. "A Pareto front based evolutionary model for airfoil self-noise prediction." In 2018 IEEE Congress on Evolutionary Computation (CEC), pp. 1-8. IEEE, 2018.

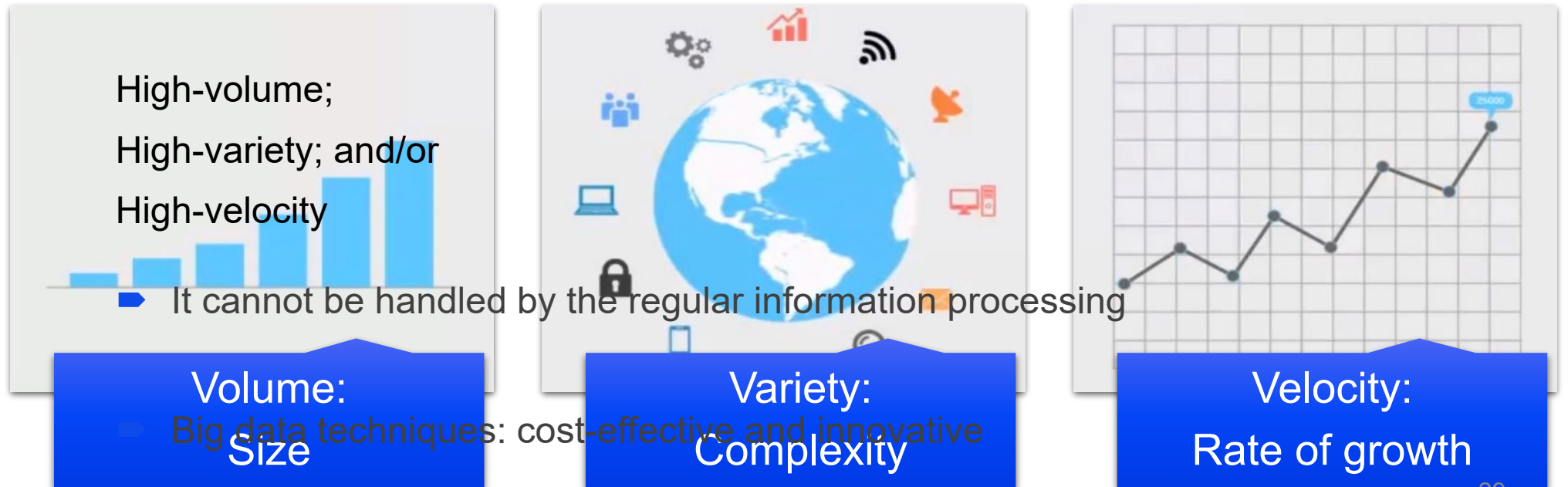
# MOOC Performance Modelling using EEG Data



Tahmassebi, Amirhessam, Amir H. Gandomi, and Anke Meyer-Baese. "An Evolutionary Online Framework for MOOC Performance Using EEG Data." In 2018 IEEE Congress on Evolutionary Computation (CEC), pp. 1-8. IEEE, 2018.

# BIG DATA

## 3Vs



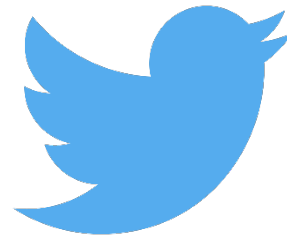
# Why BIG DATA?



>200 million



4 million



350,000



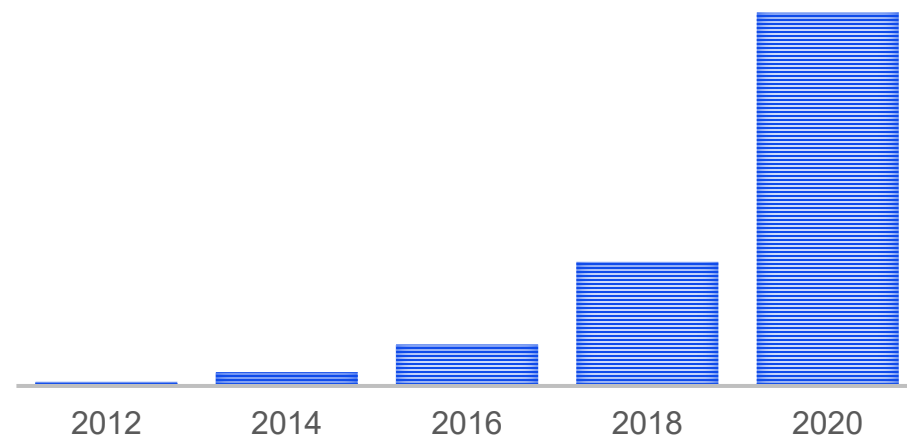
3.8 million



500 hours

How much data?

Moore's law



# Genetic Programming for Big Data Analytics (Current)

Divide-and-conquer

- find an efficient and systematic divide-and-conquer strategy, such as information theory
- structure initializations for GP

GP development

- extend GP with a multi-gene structure
- couple GP with other machine learning and/or regression analysis
- extend traditional evolutionary operators and define new operator(s) for the newly developed GP

# Multi-stage genetic programming

## Multi-Stage Genetic Programming

---

**Begin**

$$Y = f(X)$$

**for**  $i = 1 : n$  ( $n$  is the number of inputs)

  Input =  $x_i$

  Output =  $Y$

  % Run GP for  $f_i(x_i)$

  Randomly generate initial population

  Access fitness of population

**if** (The termination or convergence conditions are not satisfied)

    Select individual based on fitness

    Make random changes (Crossover, Mutation, etc.)

    Go to

**end if**

$$Y = Y - f_i(x_i)$$

**end for**  $i$

Input =  $X(x_1, x_2, \dots, x_n)$

Output =  $Y$

% Run GP for  $f_{int}(X)$

Randomly generate initial population

Access fitness of population

**if** (The termination or convergence conditions are not satisfied)

  Select individual based on fitness

  Make random changes (Crossover, Mutation, etc.)

  Go to

**end if**

$$f(X)_{MSGP} = \sum_{j=1}^n f_j(x_j) + f_{int}(X)$$

**end**

---

$$f(X) = f_1(x_1) + f_2(x_2) + \dots + f_n(x_n) + f_{int}(X) = \sum_{i=1}^n f_i(x_i) + f_{int}(X)$$

$$f_2(x_2) = f(X) - f_1(x_1)$$

$$f_3(x_3) = f(X) - f_1(x_1) - f_2(x_2)$$

⋮

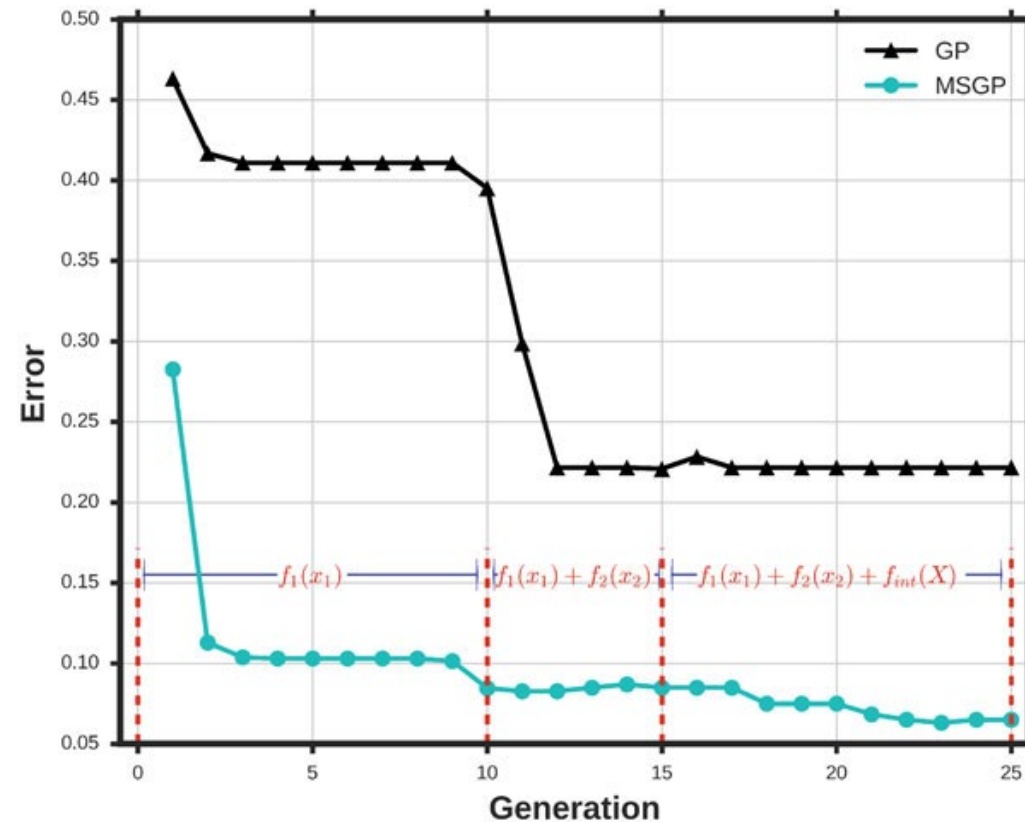
$$f_n(x_n) = f(X) - f_1(x_1) - f_2(x_2) - \dots - f_{n-1}(x_{n-1})$$

$$f_{int}(X) = f(X) - \sum_{i=1}^n f_i(x_i)$$

Gandomi A.H., Alavi A.H., "Multi-Stage Genetic Programming: A New Strategy to Nonlinear System Modeling." Information Sciences, Elsevier, 181(23): 5227-5239, 2011.



# MSGP for Big Data



Tahmassebi, A. and Gandomi, A.H., 2018. Genetic programming based on error decomposition: A big data approach. In *Genetic Programming Theory and Practice XV*(pp. 135-147). Springer, Cham.

# MSGP for Classification: Soil Liquefaction modelling

Stage 1:

$$F_1 = \cos(\arctan(((q_c^2 + 8.372)/(q_c - 8.372)))^2)^3$$

Stage 2:

$$F_2 = (-R_f + 1.393)/(R_f + (5.281/R_f))$$

Stage 3:

$$F_3 = \sin(-8.297\sigma_v^2 + -6.012 - \sigma_v') / -8.297$$

Stage 4:

$$F_4 = ((\arctan(\cos((\sigma_v^3)))^2)(\arctan(\cos(\sigma_v))^3))$$

Stage 5:

$$F_5 = \arctan(\arctan(\arctan(((0.0102 - 0.1011/a_{\max}) + 0.466)))$$

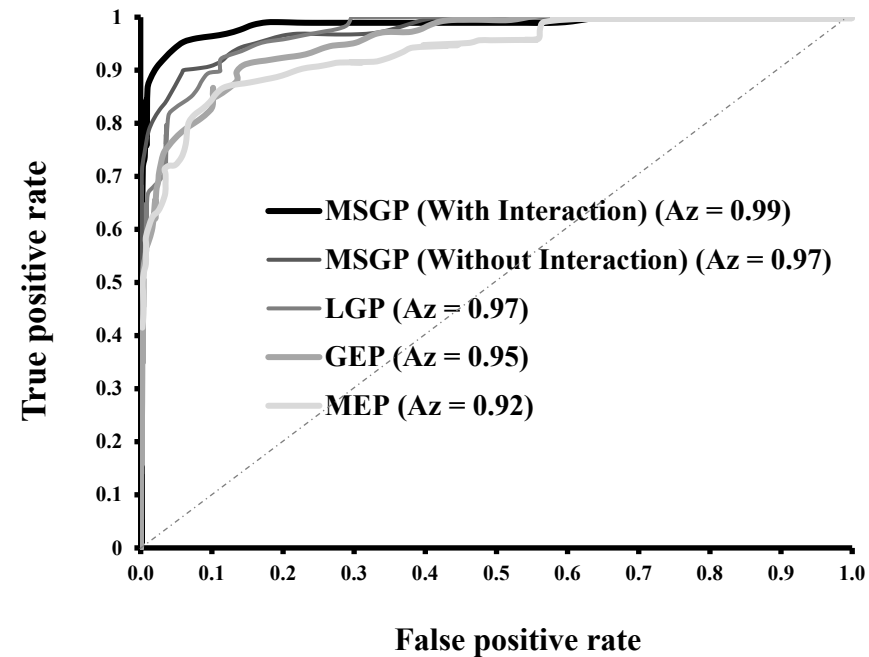
Stage 6:

$$F_6 = 0.034 \sin\left(\left(\left(M_w^2\right) - (1.589 - M_w)\right)\right)$$

Stage 7 (interaction):

$$F_{\text{int}} = (\cos((((((\cos(M_w)a_{\max})(1.534 - M_w + 5.936)) \exp(M_w))^3)/a_{\max}))/ (M_w - 1.534))$$

Figure: ROC curves

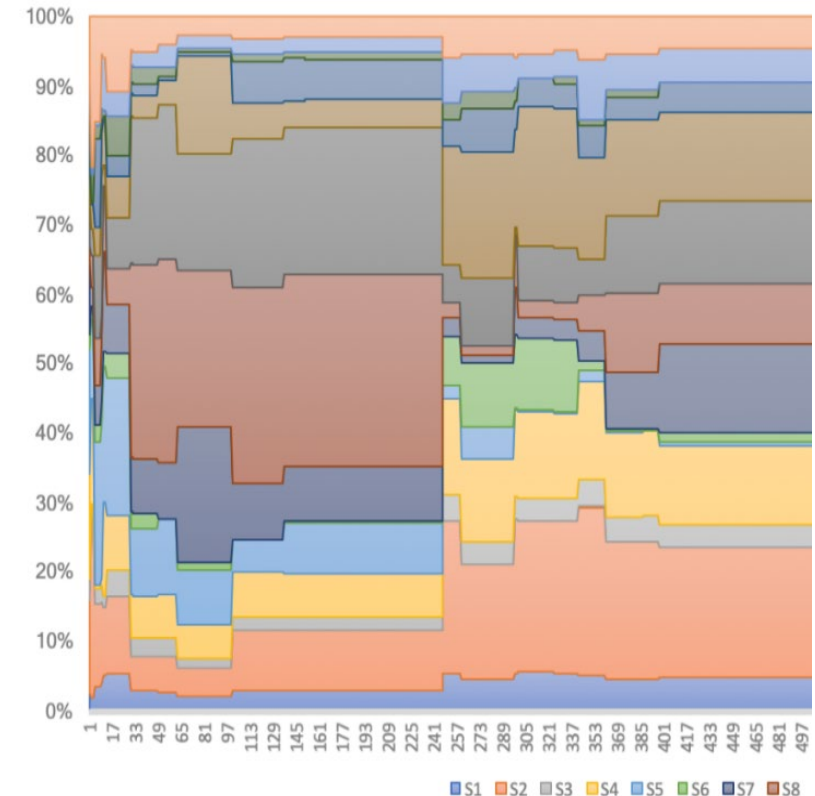


Gandomi A.H., Alavi A.H., "Multi-Stage Genetic Programming: A New Strategy to Nonlinear System Modeling." Information Sciences, Elsevier, 181(23): 5227-5239, 2011.

# Advancing Genetic Programming via Information Theory

$$\begin{pmatrix} G_{11} & G_{21} & \dots & G_{n1} \\ G_{1m} & \dots & \dots & G_{jm} \end{pmatrix} \times \begin{pmatrix} \beta_{11} & \beta_{12} & \dots & \beta_{1m} \\ \vdots & \vdots & \ddots & \vdots \\ \beta_{n1} & \beta_{n2} & \dots & \beta_{nm} \end{pmatrix} + \begin{pmatrix} \beta_{01} \\ \vdots \\ \beta_{0m} \end{pmatrix} = \begin{pmatrix} y_1^{pr} \\ \vdots \\ y_m^{pr} \end{pmatrix}$$

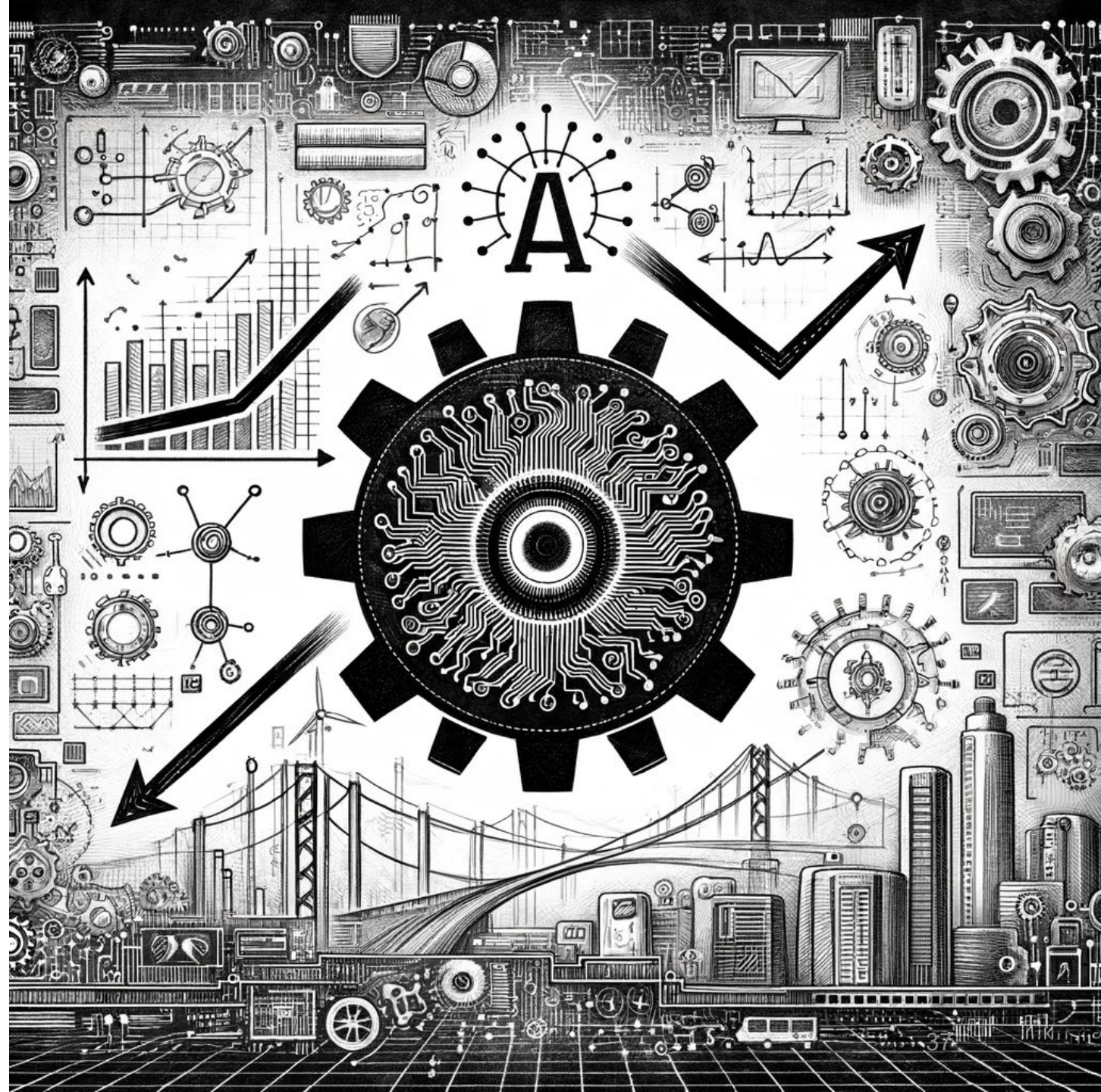
Population size	Method	WIR	WIW
1,000	MR	0.1012	0.0992
	GP	0.1084	0.1048
	RRGP	0.1012	0.1094
	MRGP-TC	0.1172	0.0958
	MRGP-SumT	0.1115	0.0959
	MRGP-MDL	0.1120	0.0960
	MRGP-SMDL	0.1347	0.0961
100	MRGP-TC	0.1085	0.0961
	MRGP-SumT	0.1076	0.0963
	MRGP-MDL	0.1030	0.0964
	MRGP-SMDL	0.1080	0.0968
	Proposed GP	<b>0.0617</b>	<b>0.0664</b>



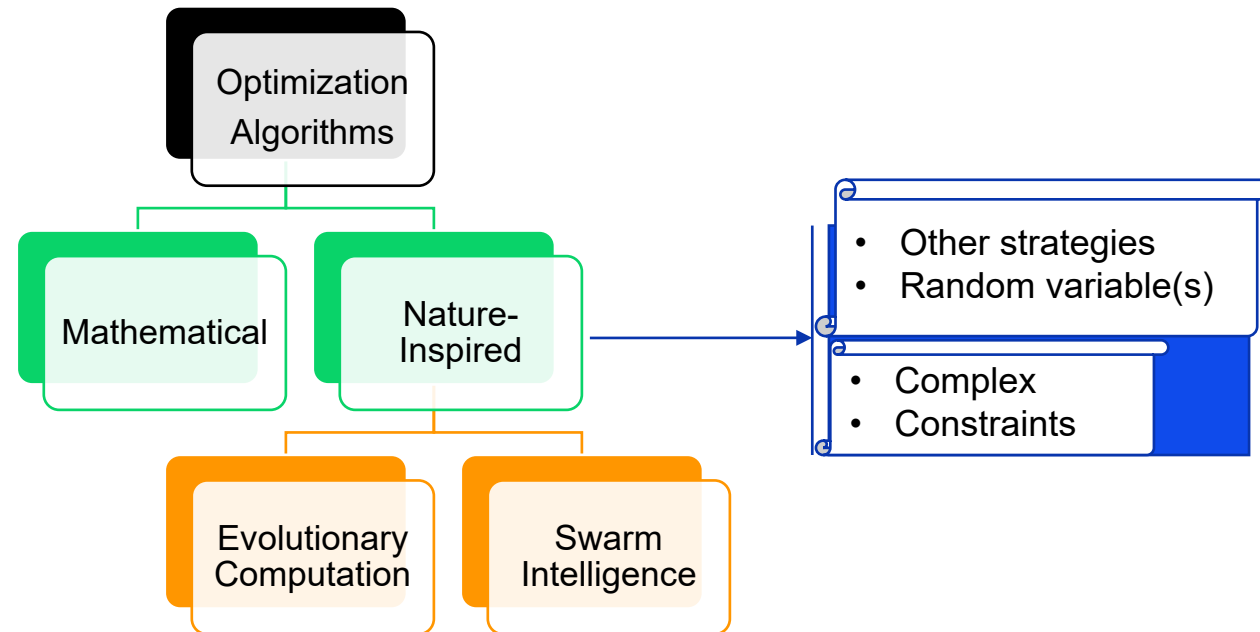
Grin, A.V. and Gandomi, A.H., 2021, June. Advancing Genetic Programming via Information Theory. In 2021 IEEE Congress on Evolutionary Computation (CEC) (pp. 1991-1998). IEEE.



# AI/EI for Engineering Optimization



# Optimization Algorithms

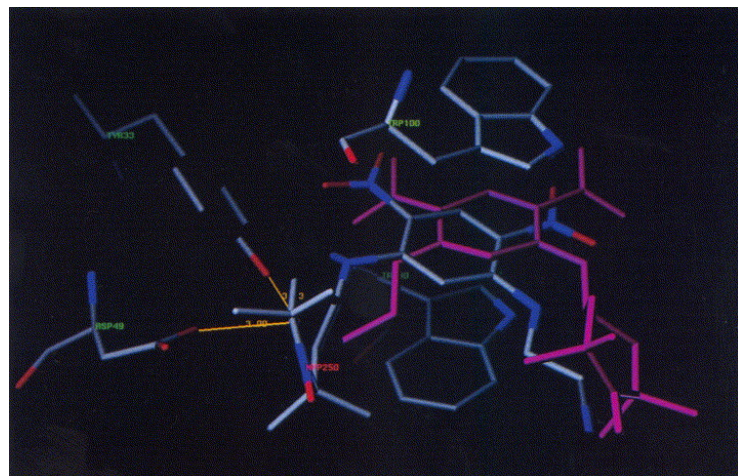


# EC in Real-World Problems



## Boeing Turbine geometry of 777 GE engine Design:

Charles W. Petit, "Touched by nature: putting evolution to work on the assembly line." US News & World Report, volume 125, issue 4, pages 43–45 (1998).



## Merck Pharmaceutical discovered first clinically-approved antiviral drug for HIV:

Jones G, Willett P, Glen RC, Leach AR, Taylor R (1997) Development and validation of a genetic algorithm for flexible docking. J Mol Biol 267: 727–748.

& so many other companies.



Uber



## Traditional Algorithms:

Genetic Algorithm (GA)  
Simulated Annealing (SA)  
Particle Swarm Optimization (PSO)

## Recent Algorithms:

Breathe Green

Hunger Games Search (HGS)  
Reptile Search Algorithm (RSA)  
Colony Predation Algorithm (CPA)  
Runge Kutta based Algorithm (RUN)  
Material Generation Algorithm (MGA)  
Arithmetic Optimization Algorithm (AOA)  
Quantum-based Avian Navigation Algorithm (QANA)

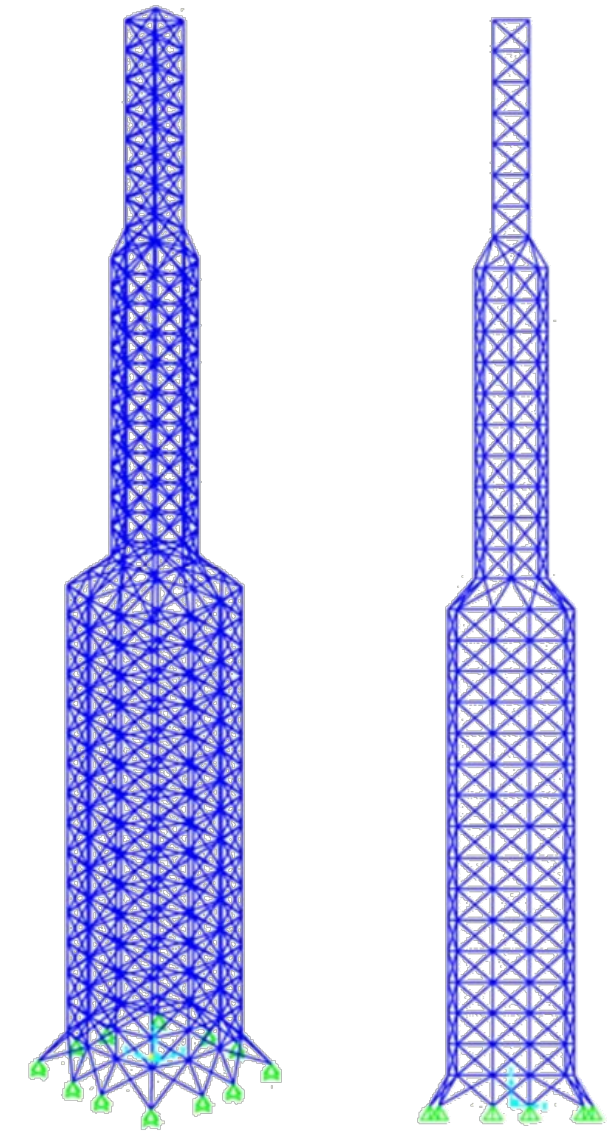
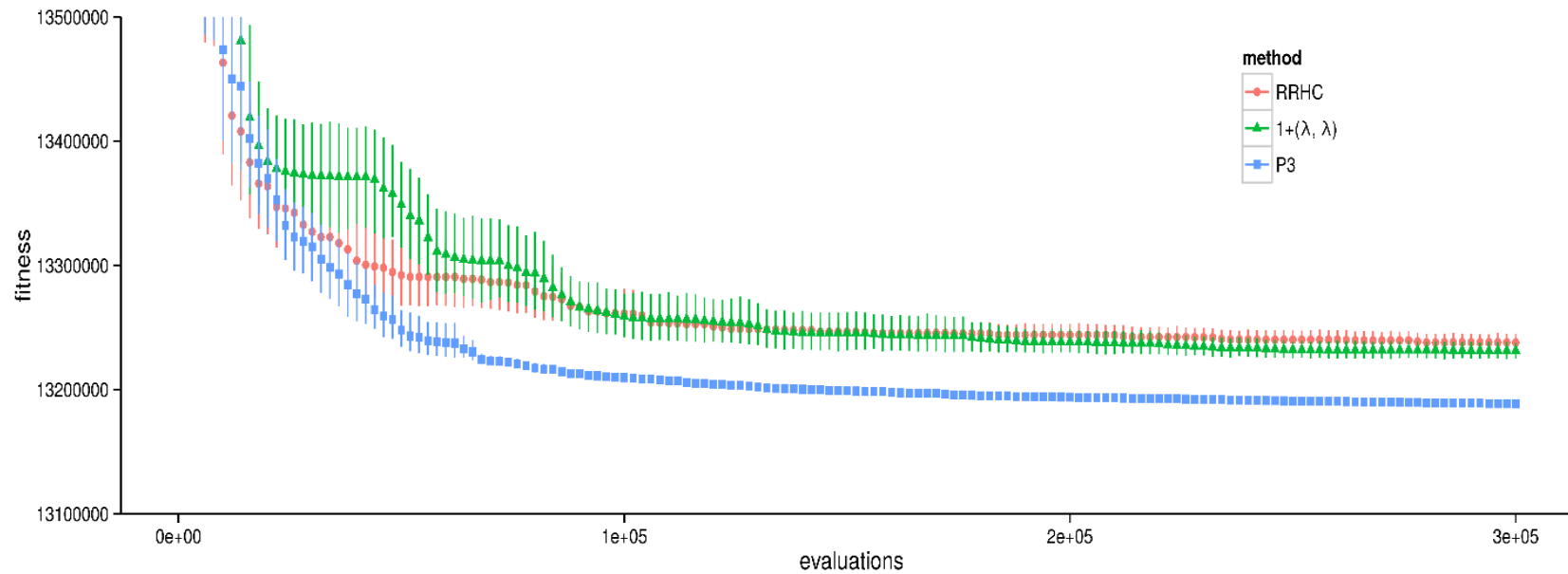
Aquila Optimizer (AO)  
Krill Herd Algorithm (KH)  
Fire Hawk Optimizer (FHO)  
Salp Swarm Algorithm (SSA)  
Interior Search Algorithm (ISA)  
Prairie Dog Optimization (PDO)  
Marine Predators Algorithm (MPA)  
Partial Reinforcement Optimizer (PRO)

Elsevier – IFAC Best Theory Paper Award in EAAI from 2020-2022



# Complex Systems: 35-Storey Space Tower

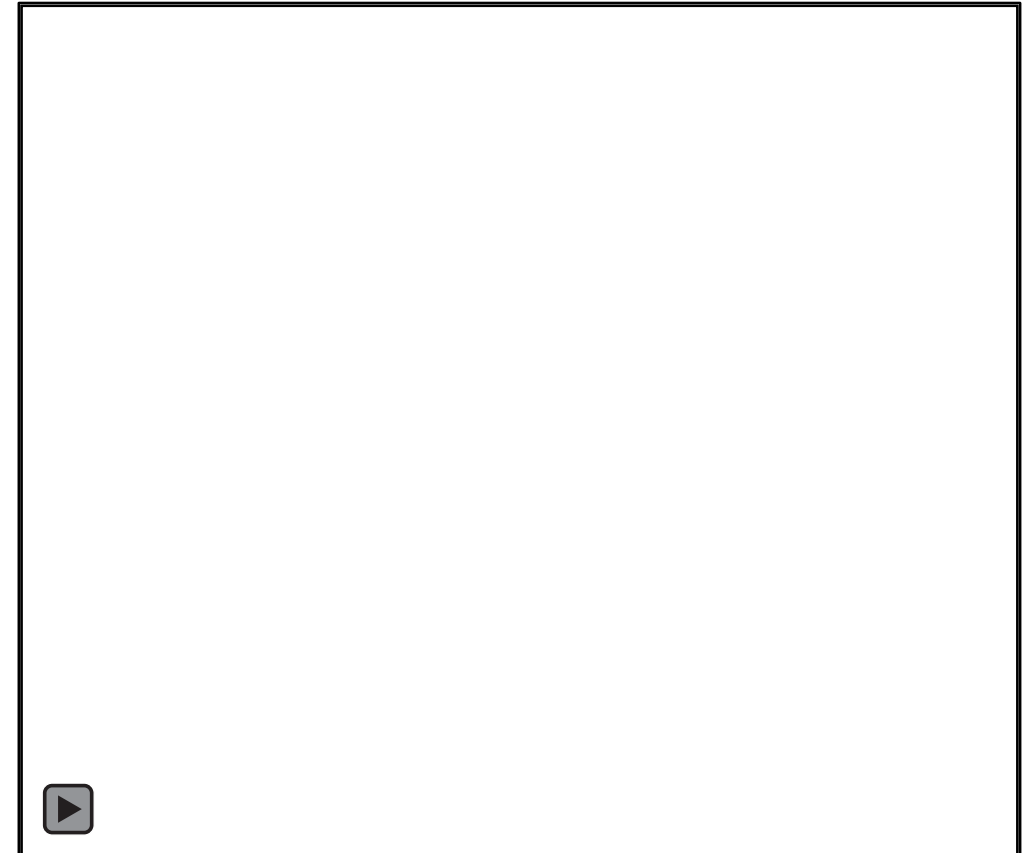
1262 members and 936 degrees of freedom



Gandomi, A. H., & Goldman, B. W. Parameter-less population pyramid for large-scale tower optimization. Expert Systems with Applications, 96, 175-184, 2018.

# Many Objective Evolutionary Optimization

- 18 evolutionary many-objective algorithms are compared against well-known combinatorial problems!
- knapsack problem,
- traveling salesman problem,
- quadratic assignment problem
- 3, 5, and 10 objectives problems are tested

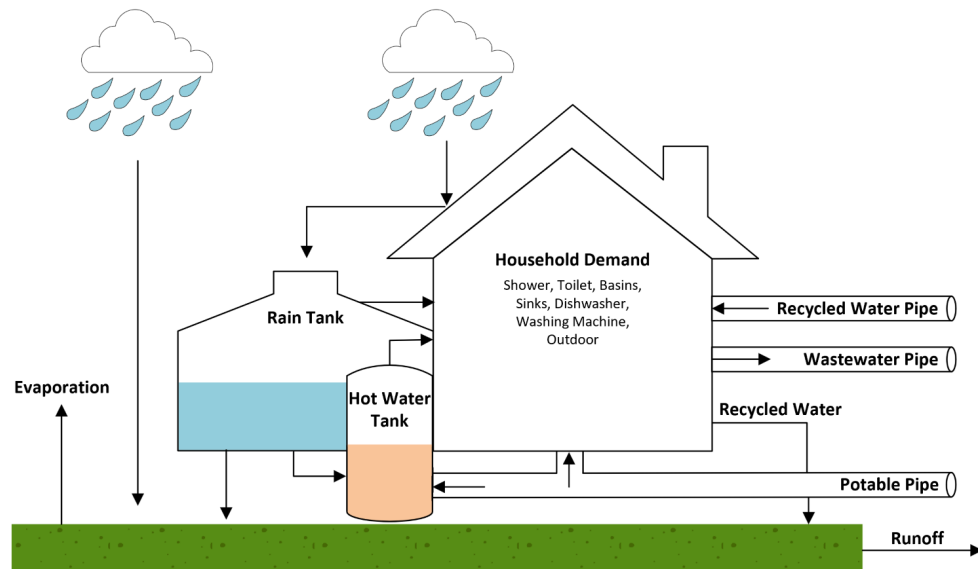


Behmanesh, R., Rahimi, I. and Gandomi, A.H., 2021. Evolutionary many-objective algorithms for combinatorial optimization problems: a comparative study. Archives of Computational Methods in Engineering, 28(2), pp.673-688.

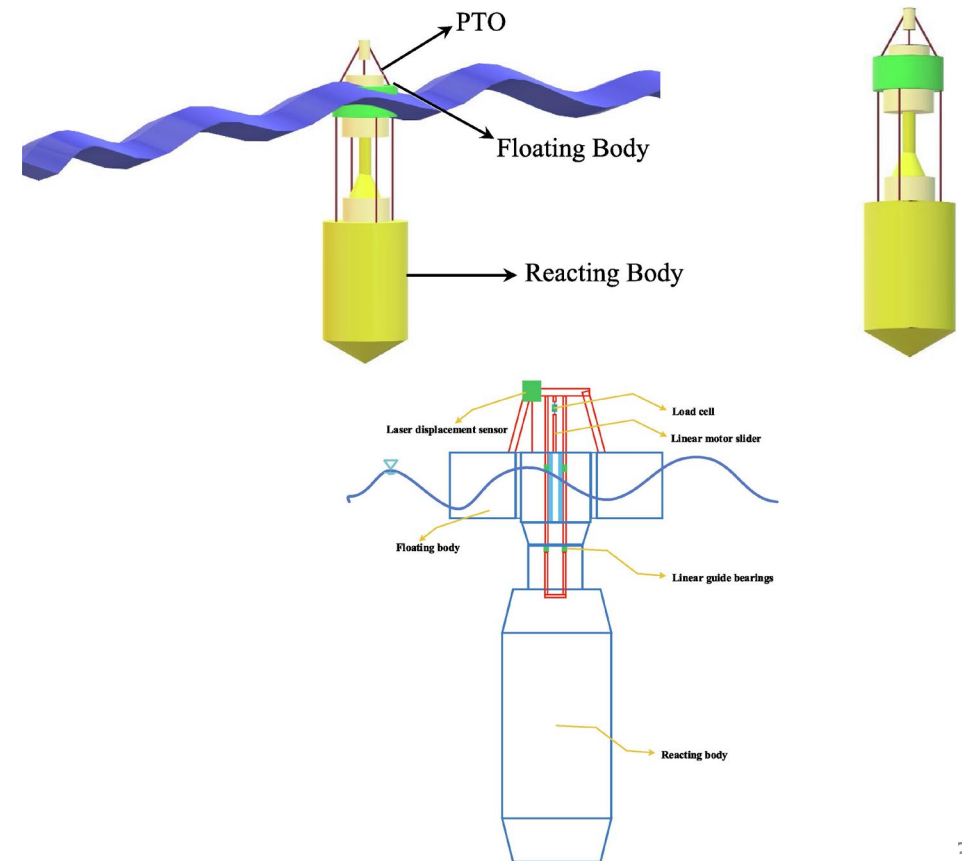
# EMO for Water and Environmental Problems

Optimisation of Local Integrated Water Management System. Objectives:

- mean daily piped potable water,
- mean daily site run-off,
- mean daily nominal costs.



Several studies on multi-objective optimization of wave energy converters (locations, layouts, shapes, etc).



# EI for Combating COVID-19

## XPRIZE-Cognizant Pandemic Challenge

F1: daily new cases

F2: stringency of planned interventions

UTS team:

I led team **Kangaroos** in this competition

Our team used

- ML to build models
- EMO to optimize the objectives

Results:

- We were the only team from Australia to reach the final
- We end up as a top-ten team
- We became one of the Honourable Mention Winners

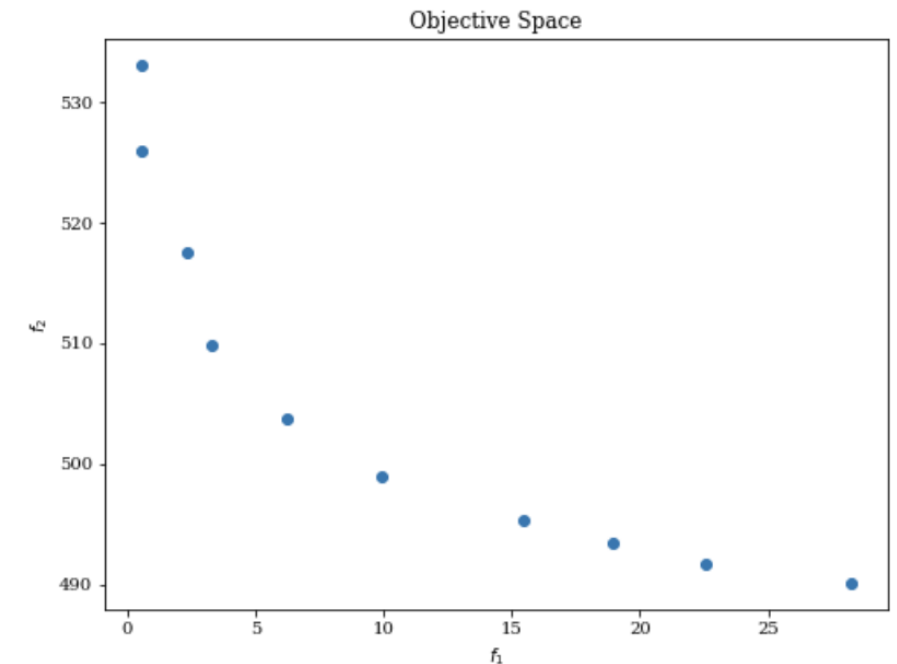


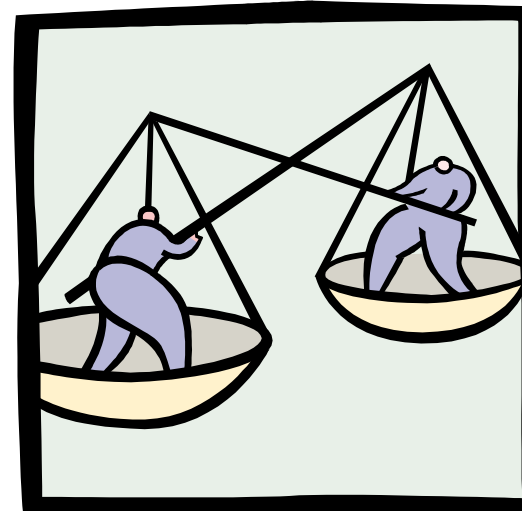
Figure 1. Sample Pareto Front for Canada

# Customization in Optimization

## AI-based Algorithms

- PROs
  - Derivative-free
  - Global
  - Flexible
- Heuristic
  - More efficient
    - Convergence
    - Speed

- CONs
  - Slow



# Domain Knowledge

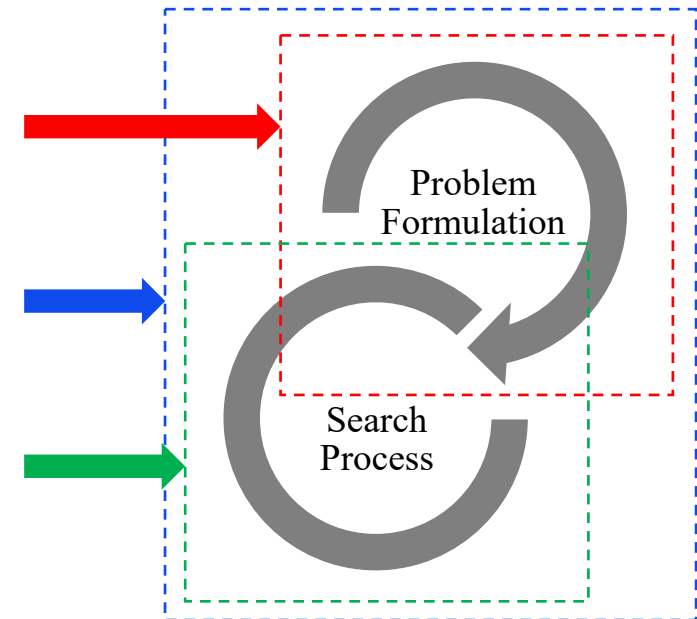
## Possible Knowledge

Expert Knowledge

Information and Mathematical Theories

Engineering Principles

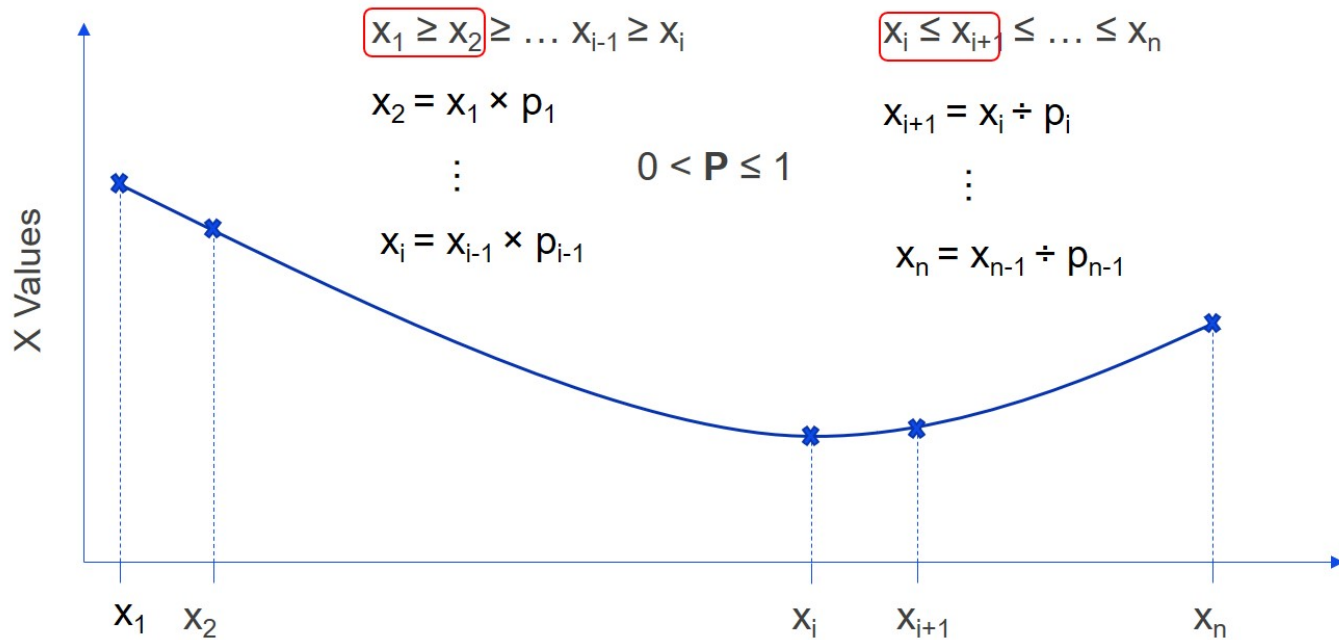
Scientific Concepts



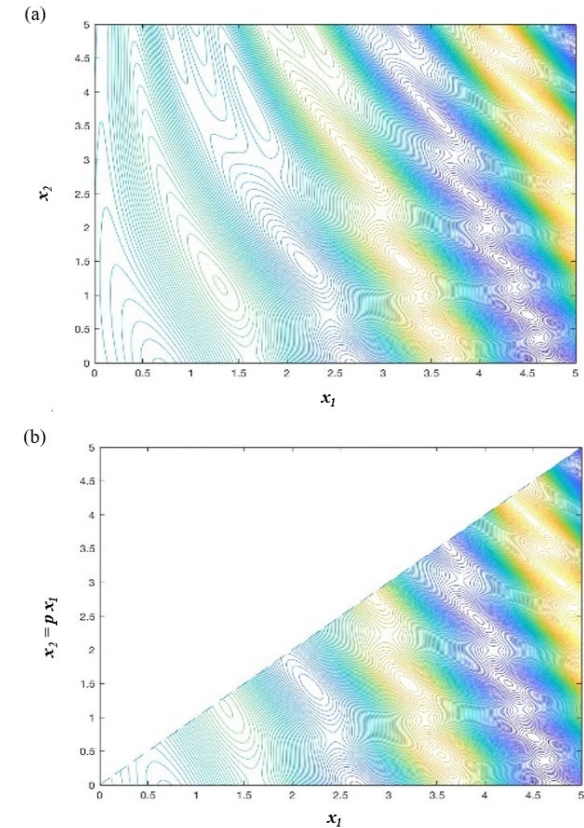
## Tutorial (most recent):

Gandomi, A.H., (2022) ACM GECCO 2022# embedding knowledge into optimization process. In *Proceedings of the Genetic and Evolutionary Computation Conference Companion*, ACM (pp. 922-936). DOI 10.1145/3520304.3533641

# Semi-Independent Variables (SIV)



**X** →  $x_1, P$



**Reduction ratio =  $2^N$**   
 **$N$ : number of SIVs**

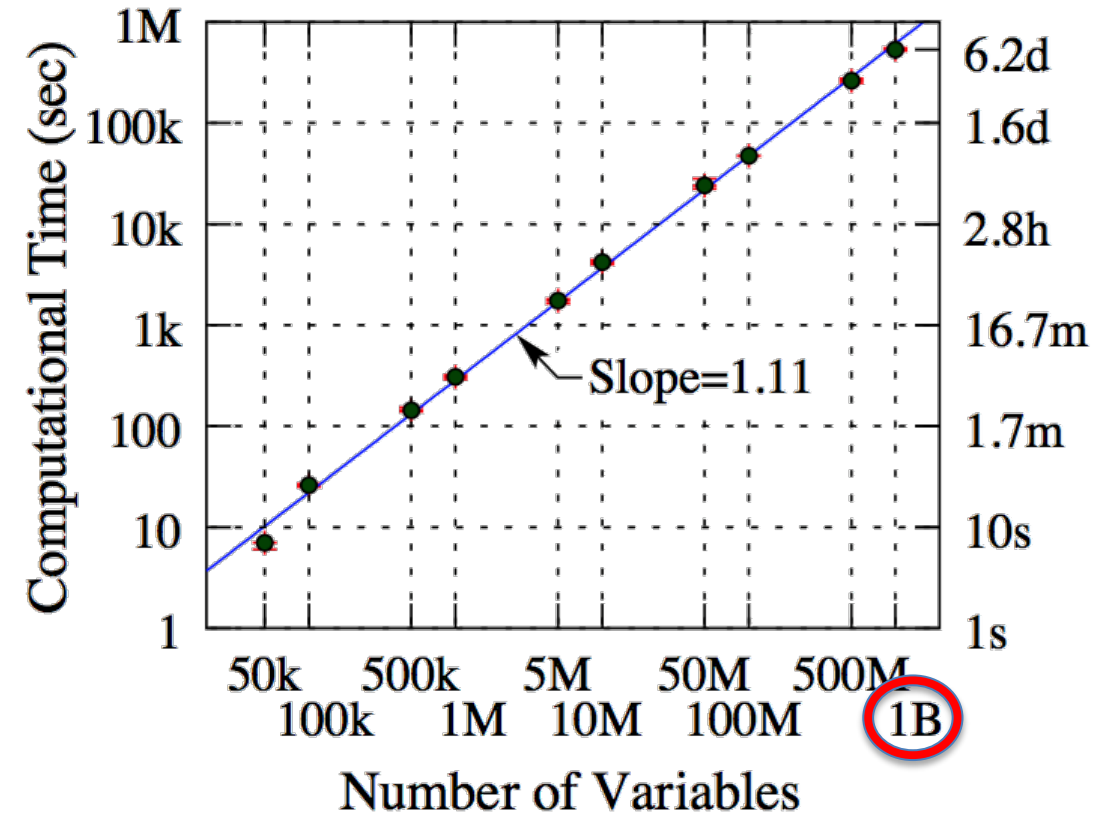
# Billion Variable Problem Solved using EAs

Resource allocation Problem:

- Casting scheduling
- Multi-knapsack problem is NP-hard
- Discrete Variables
- Pop. Size: 60 for all problems

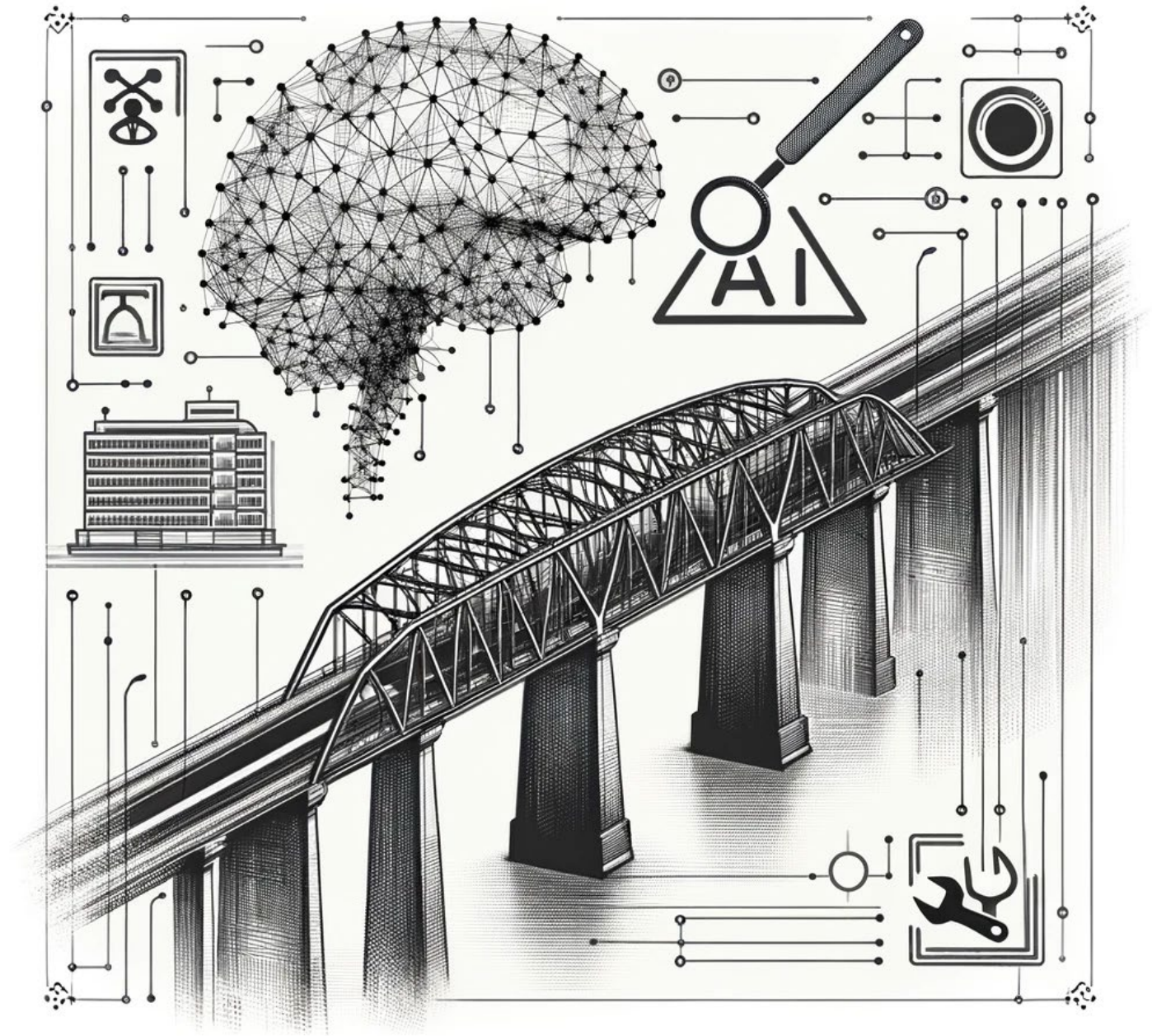
How much is a Billion?

- 4GBytes for a solution, 240GB RAM for a population





# AI for Engineering Monitoring and Maintenance



# Structural Health Monitoring



**Sungsoo Bridge, Seoul (1994)**



**Kobe Earthquake (1995)**



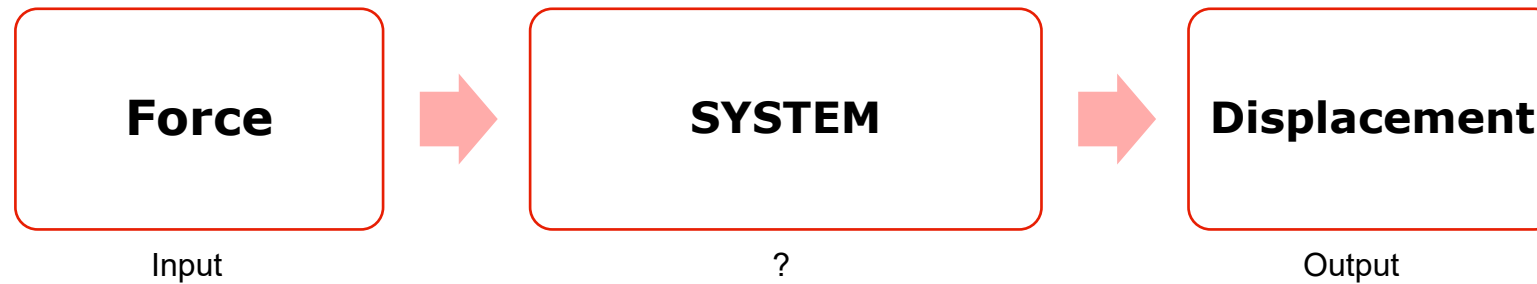
**San Francisco-Oakland Bridge (1989)**



**Highway Bridge, Minnesota (2007)**

# Inverse Analysis

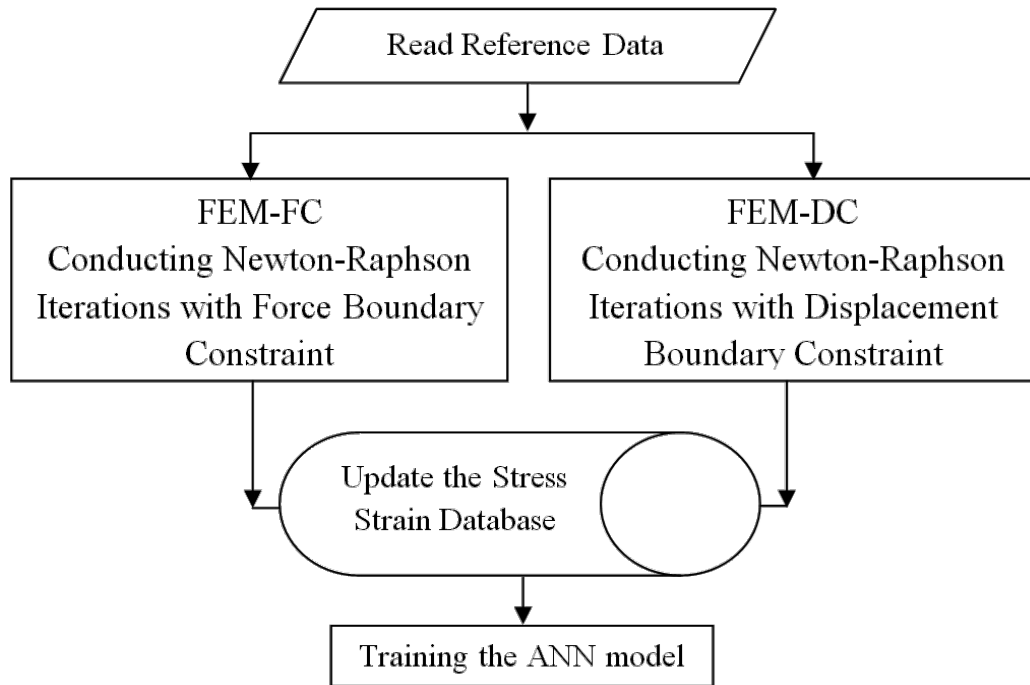
## Inverse Problem of Engineering Systems



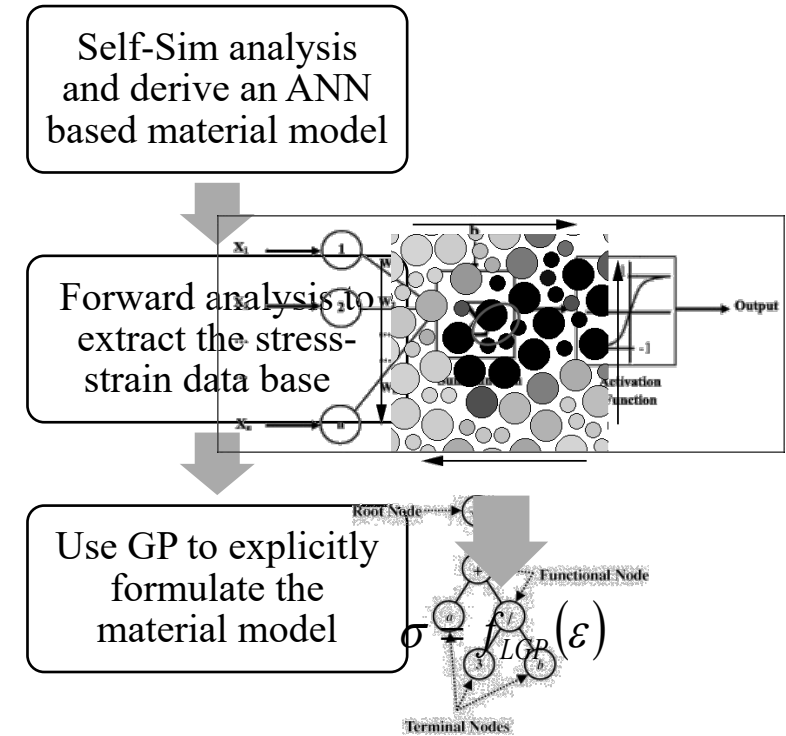
**As the system properties are usually unknown we need to do the inverse analysis**

**We need to have the Model (F.E. Model)**

# Coupled Self-Sim & GP

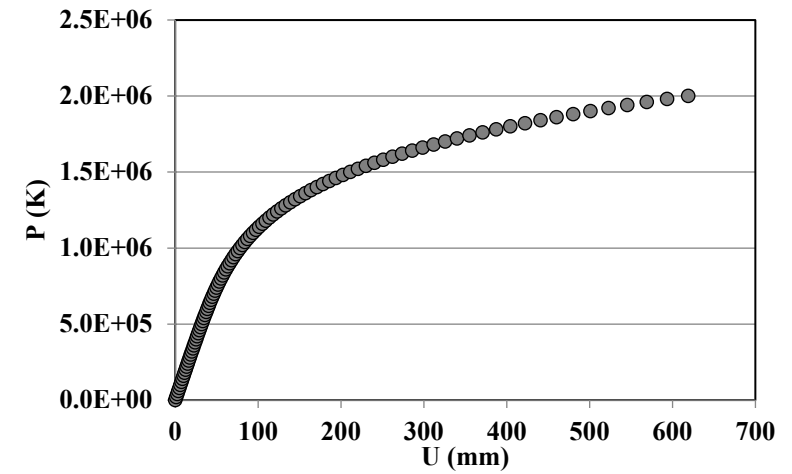
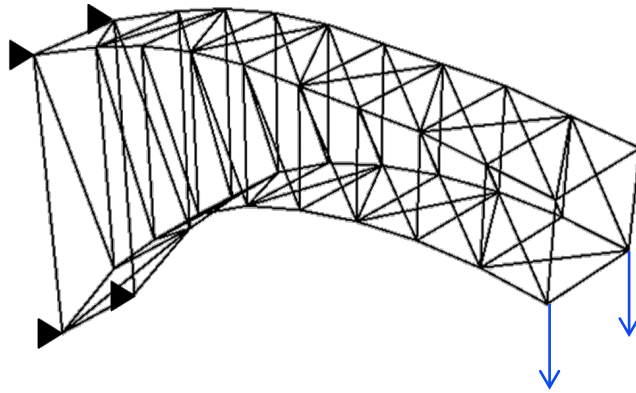


Ghaboussi, J., Pecknold, D.A., Zhang, M. and Haj-Ali, R.M., 1998. Autoprogressive training of neural network constitutive models. *International Journal for Numerical Methods in Engineering*, 42(1), pp.105-126.

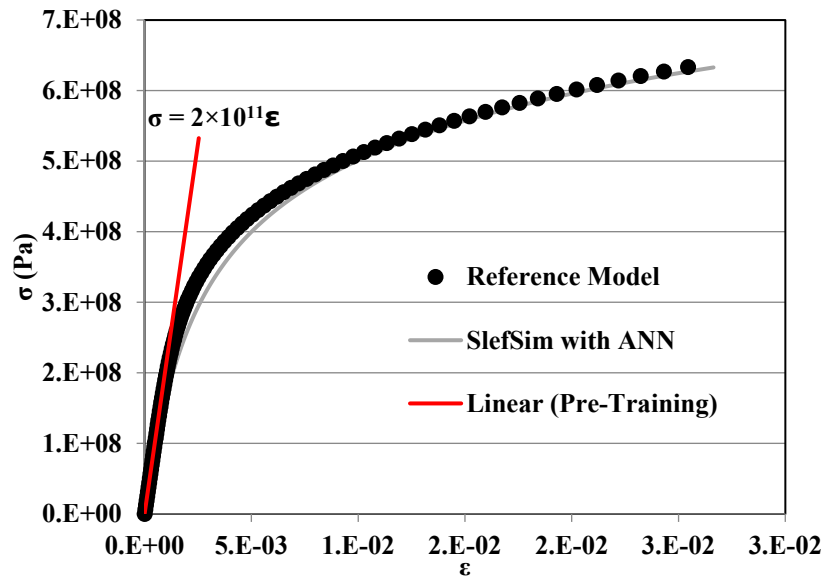


Gandomi A.H., Yun G.J., "Coupled SelfSim and genetic programming for non-linear material constitutive modelling." *Inverse Problems in Science and Engineering*, 23(7), 2015

# Case Study: 112 bar Space Truss



# GP-based Constitutive Model

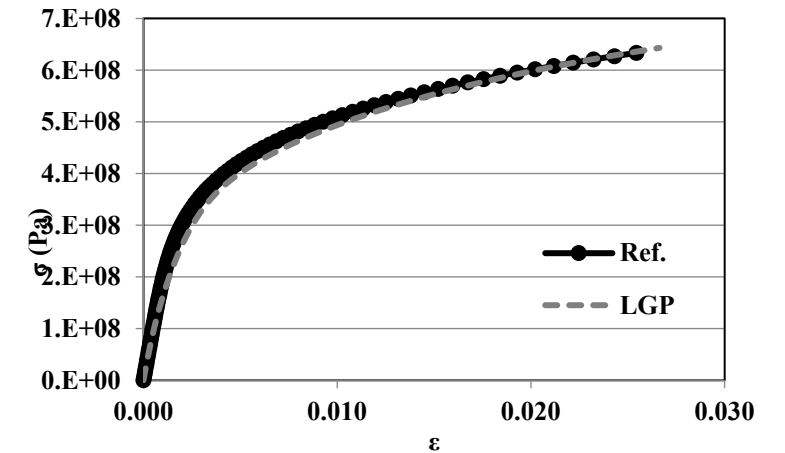


```

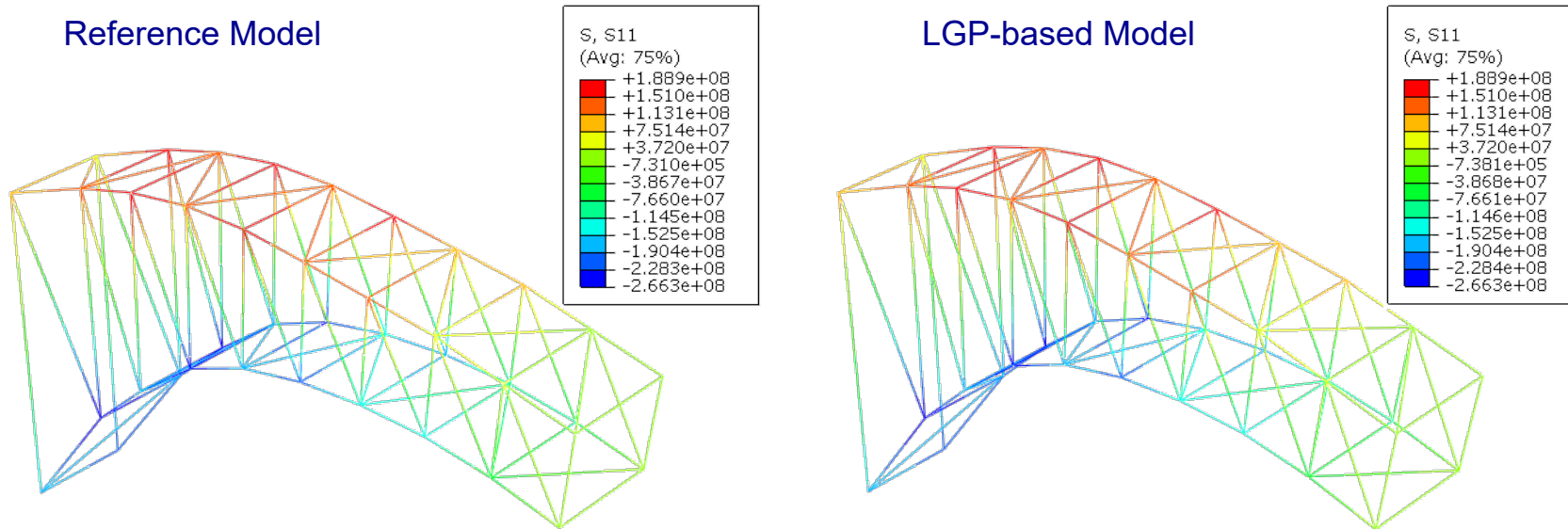
f[1]=f[2]=f[3]=f[4]=f[5]=
f[6]=f[7]=f[8]= 0;
f[0]=v[0];

I0: f[0]*=8;
I1: f[0]=sqrt(f[0]);
f[1]-=f[0];
I2: f[0]-=0.25;
I3: f[0]*=f[0];
f[1]+=f[0];
I4: f[1]+=f[0];
f[0]+=f[1];
I5: f[0]=fabs(f[0]);
f[0]-=f[1];
I6: f[1]-=f[0];
f[0]*=f[0];
I7: f[0]*=f[0];
f[0]+=f[1];
I8:
I9:

return f[0];
}
    
```

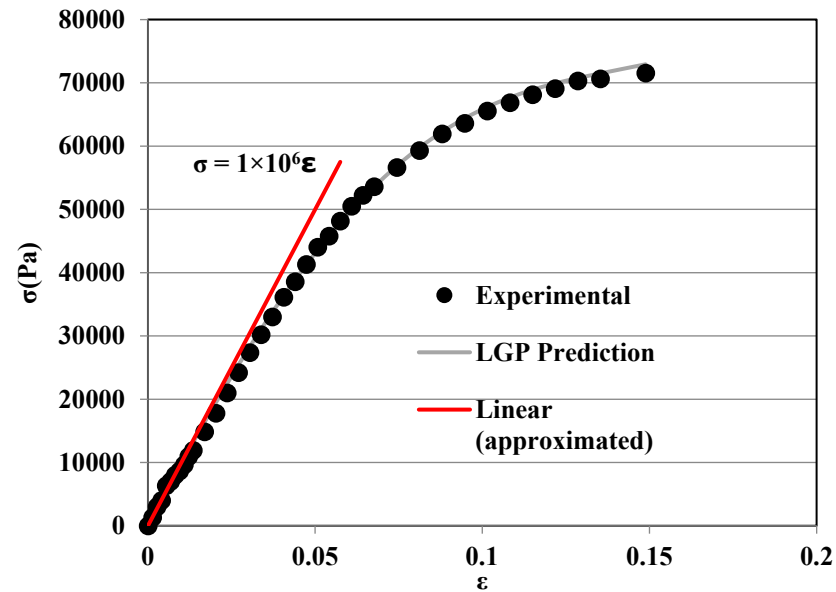


# Forward FE simulation using GP-based constitutive model

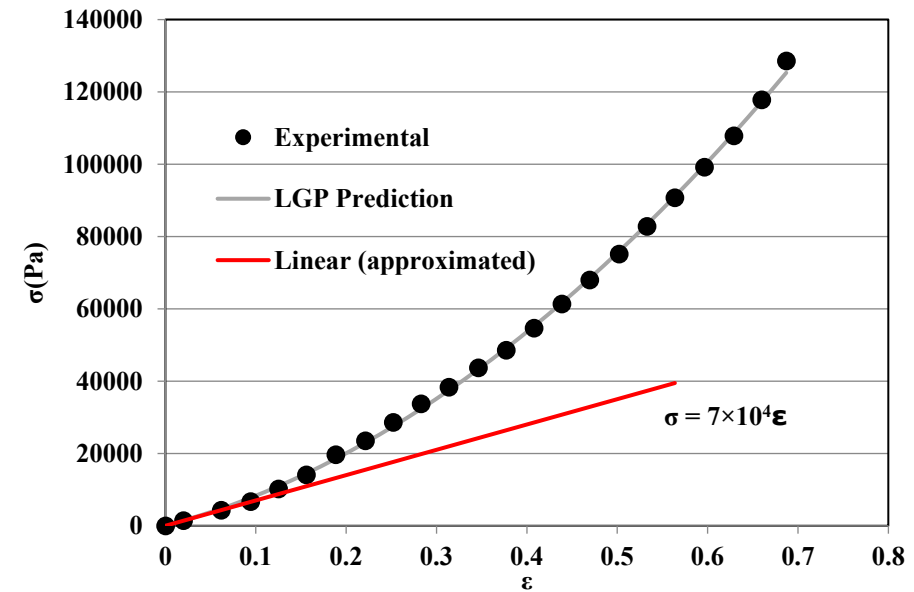


# Other Cases

## Soil Modelling



## Aortic Modelling



Yun G.J., Gandomi A.H., "Coupled selfsim and genetic programming for non-linear material constitutive modeling" In Proceedings of the Joint Conference of the Engineering Mechanics Institute and 11<sup>th</sup> ASCE Joint Specialty Conference on Probabilistic Mechanics and Structural Reliability, Notre Dame, IN, Paper ID. 657, 2012.



# EI is only one of the AI tools!



## AI methodologies/Tools:

- Machine Learning
- Deep Learning
- Natural Language Processing
- Computer Vision
- Predictive Analytics
- Evolutionary Intelligence
- Fuzzy Logic
- Expert Systems
- Robotics
- Signal Processing



# Other studies!

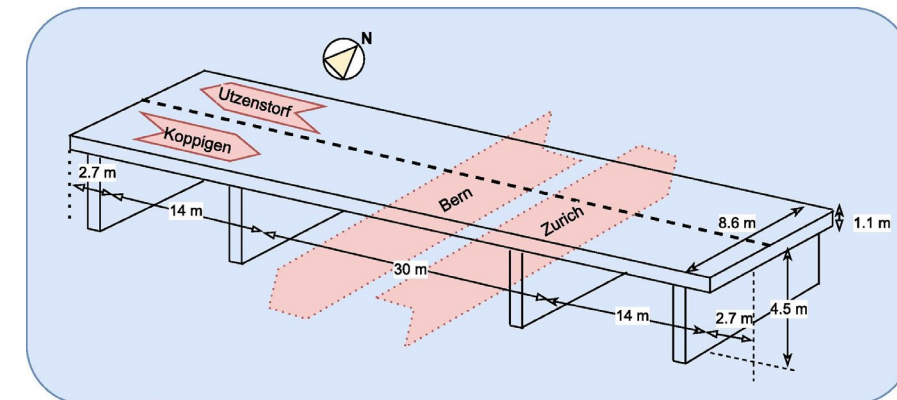
Mousavi, M., Taskhiri, M.S. and Gandomi, A.H., 2023. Standing tree health assessment using contact–ultrasonic testing and machine learning. *Computers and Electronics in Agriculture*, 209, p.107816.

Using other AI based tools such as the following SHM studies:

- Assessment of standing trees and wooden poles using contact–ultrasonic testing and machine learning and convolutional neural network!



- Combining advanced signal processing (VMD and Johansen cointegration) and machine learning approaches for structural health monitoring!



Mousavi, M. and Gandomi, A.H., 2021. Prediction error of Johansen cointegration residuals for structural health monitoring. *Mechanical Systems and Signal Processing*, 160, p.107847.

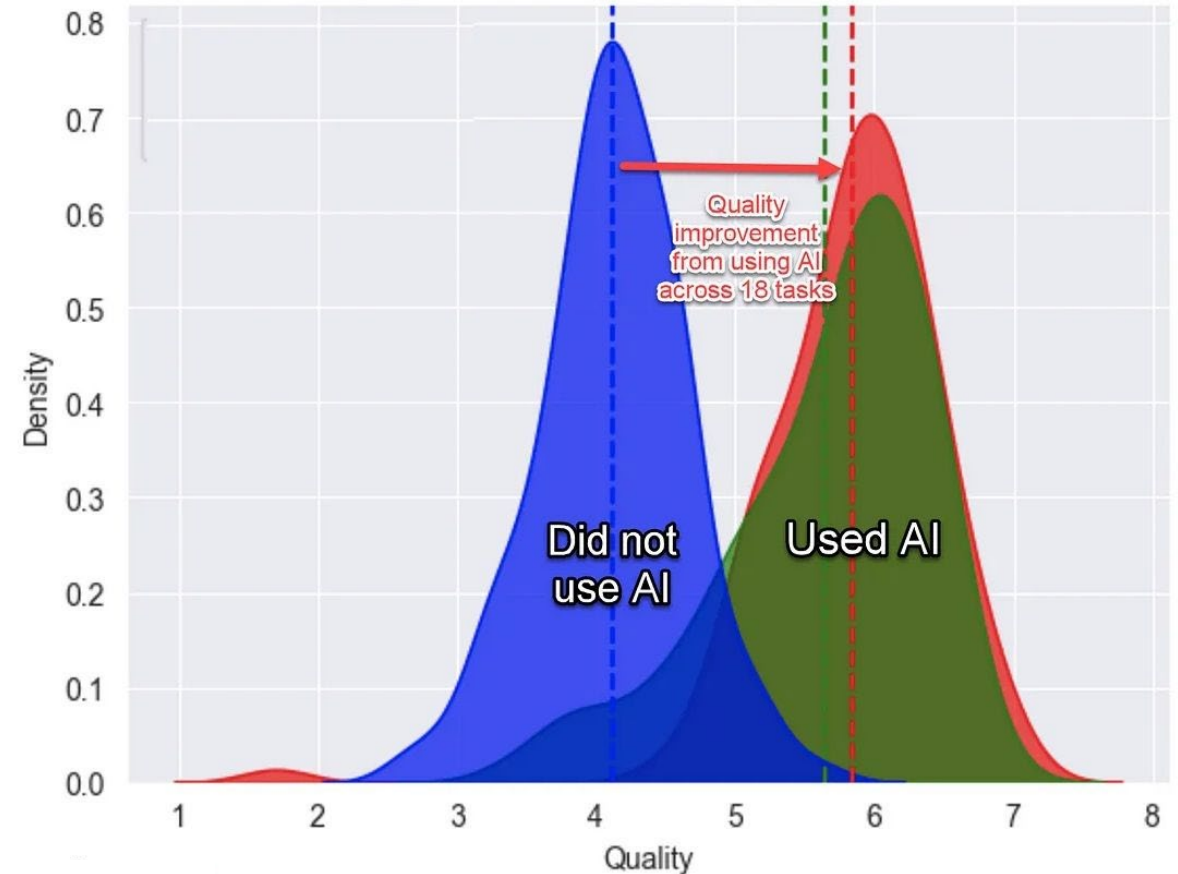
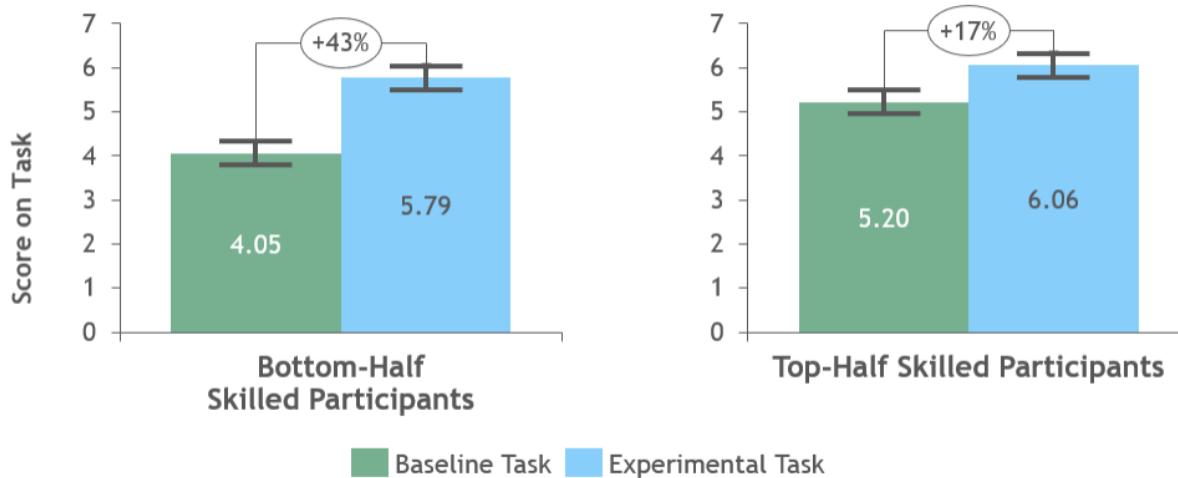
# AI Impacts in Engineering

- **Enhanced Design and Simulation**
- **Predictive Maintenance**
- **Improved Efficiency and Automation**
- **Quality Control**
- **Risk Assessment**
- **Resource Optimization**
- **Smart Infrastructure**
- **Environmental Impact**
- **Supply Chain and Logistics**
- **Customization**
- **Safety Enhancements**
- **Data Management and Decision Making**
- **Intelligent Monitoring Systems**
- **Workforce Transformation**
- **Research and Development**



# Effect of AI in Performance

**25+% increase in speed,**  
**40+% improvement in output quality, and**  
**12+% more tasks completed**



Dell'Acqua, et al., Navigating the Jagged Technological Frontier: Field Experimental Evidence of the Effects of AI on Knowledge Worker Productivity and Quality (September 15, 2023). Harvard Business School Technology & Operations Mgt. Unit Working Paper No. 24-013



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Symposium on  
Computational  
Intelligence and  
Informatics  
(IEEE CINTI 2023)  
Óbuda University,  
Budapest, Hungary**

**Thank you!**

**Amir H Gandomi**

***Professor of Data Science at University of Technology Sydney  
Distinguished Professor at Óbuda University, Budapest***



Robert Bosch Engineering company, Budapest, Hungary  
20 November, 2023

UTS CRICOS 00099F